MITSUBISHI Loop Control Module

User's Manual

(Hardware)

Q62HLC

Thank you for purchasing the Mitsubishi general-purpose programmable controller MELSEC-Q series.

Prior to use, please read this manual thoroughly and familiarize yourself with the product.



Mitsubishi Programmable Controller

MODEL	Q62HLC-U-HW		
MODEL	13JP75		
CODE	131773		

IB(NA)-0800319-C(0802)MEE

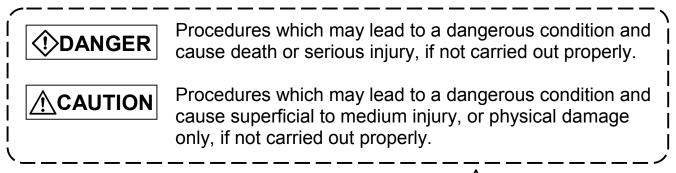
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SAFETY PRECAUTIONS •

(Read these precautions before using.)

When using Mitsubishi equipment, thoroughly read this manual and the associated manuals introduced in this manual. Also pay careful attention to safety and handle the module properly.

These SAFETY PRECAUTIONS classify the safety precautions into two categories: "DANGER" and "CAUTION".



Depending on circumstances, procedures indicated by \triangle **CAUTION** may also be linked to serious results.

In any case, it is important to follow the directions for usage.

Store this manual in a safe place so that you can take it out and read it whenever necessary. Always forward it to the end user.

[DESIGN PRECAUTIONS]

 Do not write data to the "read-only area" in the buffer memory of the intelligent function module.
 Do not turn on/off the "reconved" signals among the I/O signals to/from

Do not turn on/off the "reserved" signals among the I/O signals to/from the programmable controller CPU.

Doing so can malfunction the programmable controller system.

 An abnormal output may occur depending on failure of the output element or that of the internal circuit. Install external monitoring circuitry for output signals that may lead to major accidents.

- Do not bunch the control wires or communication cables with the main circuit or power wires, or install them close to each other. They should be installed 100 mm(3.94 inch) or more from each other. Not doing so could result in noise that may cause malfunction.
- During the power supply ON/OFF, current may run instantaneously from the output terminal.

Wait and see whether the analog output is constant, then start the control.

[INSTALLATION PRECAUTIONS]

 Use the programmable controller in an environment that meets the general specifications contained in the CPU user's manual.
Using this programmable controller in an environment outside the range of the general specifications may cause electric shock, fire, malfunction, and damage to or deterioration of the product.
 When installing the module, securely insert the module fixing tabs into the mounting holes of the base module while pressing the installation lever located at the bottom of the module downward.
Improper installation may result in malfunction, breakdown or the module coming loose and dropping. Securely fix the module with screws if it is subject to vibration during use.
 Tighten the screws within the range of specified torque.
If the screws are loose, it may cause the module to fallout, short circuits, or malfunction. If the screws are tightened too much, it may cause damage to the screw and/or the module, resulting in fallout, short circuits or malfunction.
 Be sure to shut off all phases of the external power supply used by the system before mounting or removing the module.
Not doing so may cause electric shock or damage to the module. In the system where a CPU module supporting the online module change is used and on the MELSECNET/H remote I/O stations, modules can be replaced online (during energizing). However, there are some restrictions on replaceable modules and the replacement procedures are predetermined for each module.
For details, refer to the chapter of the online module change in Loop Control Module User's Manual.

• Do not directly touch the conductive area or electronic components of the module. Doing so may cause malfunction or failure in the module.

[WIRING PRECAUTIONS]

• Be careful not to let foreign matters such as sawdust or wire chips get inside the module.

They may cause fires, failure or malfunction.

• The top surface of the module is covered with protective film to prevent foreign objects such as cable offcuts from entering the module when wiring. Do not remove this film until the wiring is complete. Before operating the system, be sure to remove the film to provide adequate heat ventilation.

 Be sure to fix communication cables or power supply cables leading from the module by placing them in the duct or clamping them. Cables not placed in the duct or without clamping may hang or shift, allowing them to be accidentally pulled, which may cause a module malfunction and cable damage.

[WIRING PRECAUTIONS]

	DN
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• Do not grab on the cable when removing the communication or power cable connected to the module.

When disconnecting a cable without a connector, first loosen the screws on the part that is connected to the module.

Pulling the cable when it is still connected to the module may cause damage to the module or cable, or misoperation due to cable contact failure.

Always ground the FG terminal and the shielded cable for the programmable controller.

There is a risk of electric shock or malfunction.

- When turning on the power and operating the module after wiring is completed, always attach the terminal cover that comes with the product. There is a risk of electric shock if the terminal cover is not attached.
- Use applicable solderless terminals and tighten them with the specified torque. If any solderless spade terminal is used, it may be disconnected when the terminal screw comes loose, resulting in failure.
- When wiring, be sure to verify the rated voltage of the product as well as the terminal layout. Fire or failure may result if incorrect voltage is input or incorrect wiring is performed.
- Connecting terminals with incorrect voltage may result in malfunction or mechanical failure.

REVISIONS

* The manual number is given on the bottom right of the top cover.

Print Date	* Manual Number	Revision
Oct., 2005	IB (NA)-0800319-A	First edition
Nov., 2007	IB (NA)-0800319-B	PARTIAL CORRECTION SAFETY PRECAUTIONS, Section 2.2, Chapter 4, Chapter 5
Feb., 2008	IB (NA)-0800319-C	PARTIAL CORRECTION SAFETY PRECAUTIONS, Conformation to the EMC Directive and Low Voltage Instruction, Section 2.1, 2.2, 2.3, 2.4, 3.1, Chapter 6

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About the Manuals

The following manuals are related to this product. Referring to this list, please request the necessary manuals.

Detailed Manual

Manual Name	Manual Number (Model Code)
Loop Control Module User's Manual	SH-080573ENG (13JR85)

Conformation to the EMC Directive and Low Voltage Instruction

(1) About sequence system

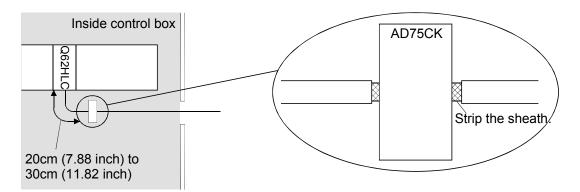
When incorporating the Mitsubishi programmable controller into other machinery or equipment and keeping compliance with the EMC and low voltage directives, refer to Chapter 9, "EMC Directive and Low Voltage Instruction" of the QCPU User's Manual (Hardware Design, Maintenance and Inspection).

The CE logo is printed on the rating plate of the programmable controller, indicating compliance with the EMC and low voltage directives.

(2) About this product

The following wiring is required for conformance of this product with the EMC Directive and Low Voltage Directive.

(a) Use shielded cables for all external wiring and use the AD75CK cable clamp to ground this product to an enclosure.



(b) Using the AD75CK, you can tie four cables of about 7mm outside diameter together for grounding.

1. OVERVIEW

This user's manual provides the specifications, handling, part names and others of the following loop control modules (hereafter abbreviated to the Q62HLC) used with the MELSEC-Q series CPU modules.

Q62HLC loop control module

2. SPECIFICATIONS

The specifications of the Q62HLC are indicated below.

2.1 Performance Specifications

Item			Specifications		
Analog I/O points			2 channels/module		
		Specific	ation for analog input *2		
Input point	S		2 points (2 channels)		
Analog inp			Refer to Section 2.2		
Digital out			16-bit signed binary		
	thermocouple		K,J,T,S,R,N,E,B,PL II,W5Re/W26Re		
Input char			Refer to Section 2.2		
Maximum	resolution		Refer to Section 2.2		
	Indication	Ambient temperature: 23°C ±2°C	Refer to Section 2.3		
Accuracy	accuracy	Ambient temperature: 0°C to 55°C	Refer to Section 2.3		
*1	Cold junction temperature	Ambient temperature: 23°C ±2°C	±0.5°C		
	compensation accuracy	Ambient temperature: 0°C to 55°C	±1.0°C		
Conversio	n speed		25ms/2 channels		
Conversion	n speed		(Stable regardless of the number of used channels)		
Sampling	period		25ms/2 channels		
-			(Stable regardless of the number of used channels) Micro voltage: ±12V,Voltage: ±15V,Current: ±30mA		
Absolute maximum input Input impedance			Thermocouple, Micro voltage, Voltage: $150,$ Current: 250 M		
Normal mode rejection ratio		n	60dB or more (50/60Hz)		
Common mode refection ratio			120dB or more (50/60Hz)		
Input filter (primary delay digital filter)			0.0 to 100.0s (0: Input filter OFF)		
		. /	Thermocouple: -500.0 to 500.0°C		
Sensor compensation value setting		e setting	Micro voltage, Voltage, Current: -50.00 to 50.00%		
Operation at input disconnection		ection	Refer to Section 2.4		

	Item Specifications		
	Specification for analog output *2		
Output po	ints	2 points (2 channels)	
Digital inp	ut	16-bit signed binary	
Analog ou	Itput	Current	
Output characteristic		Digital input value: 0 to 1000 (When using simplified analog output 0 to 4000), Output range:4 to 20mA	
Maximum	resolution	4 <i>µ</i> A	
Output	Ambient temperature: $23^{\circ}C \pm 2^{\circ}C$	Full scale $ imes$ (±0.2%)	
accuracy Ambient temperature: Full scale \times (±0.4%)		Full scale $ imes$ (±0.4%)	
Conversio	n speed	25ms/2 channels (Stable regardless of the number of used channels)	
Allowable	load resistance	600Ω or less	
Output impedance		5ΜΩ	

*1: Calculation the accuracy in the following method.

(Accuracy) = (Indicated accuracy) + (Cold junction temperature compensation accuracy) e.g.) Accuracy when measuring a temperature in the following conditions:

- Input sensor used: Thermocouple T type (-200 to 400°C) (Select "2" at input range setting.)
- Operating ambient temperature : 35°C
- Temperature measurement value : 300°C
- The accuracy values will become as follows from the above conditions
- Indicated accuracy $\pm 1.0^{\circ}$ C (Value shown in the table of Section 2.3 (2))
- Cold junction compensation temperature accuracy

 $\pm 1.0^{\circ}$ C (Value shown in the table of Section 2.1)

Accuracy = $(\pm 1.0^{\circ}C) + (\pm 1.0^{\circ}C) = \pm 2.0^{\circ}C$

*2: This indicates the specifications for analog input/output when using as a simplified analog input/output function.

Control method Continuous proportional control PID constant range PID constant setting Proportional band (P) Auto tuning setting available Thermocouple: 0.1 to Full-scale °C Micro voltage, Current: 0.1 to 1000.0% Integral time (I) 0.0 to 3276.7s Derivative time (D) 0.0 to 3276.7s Set value setting range Thermocouple: Input range of thermocouple to use Micro voltage, Voltage, Current: 0.0 to 100.0% Dead band setting range Thermocouple: 0.0 to 100.0°C Micro voltage, Voltage, Current: 0.00 to 10.00% Time accuracy ±0.2% Insulation Insulation method Dielectric withstand voltage Insulation Insulation method 500VAC for 1 minute 500VAC 20MΩ or more FeRAM read/write count Max. 10 ¹⁰ times 500VAC 20MΩ or more 500VAC 20MΩ or more FerRAM read/write count Max. 10 ¹⁰ times 500VAC 30 to 0.75 mm ² 500VAC 20MΩ or more Applicable crimping terminal 16 points/slot (I/O assignment: 16 intelligent points) 24 VDC +20%, -15% External power supply Ripple, spike 500mVP-P or less Intrush current: 0.2A, 4ms or less 0.07A Integral current consumption 0.27A 0.27A	input/ot			Snooi	ficationa	
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Weight 0.25kg						
Weight 0.25kg	Internal cu	rrent consumption	0.27A			
		•	0.25kg			
	U U	imensions	27.4[1.08](W)×98[3.86](H)×112[4.41](D) mm[in.]			

2.2 Types, Measured Ranges and Data Resolutions of Usable Input Sensors

Input		Input range	Digital value	Data resolution	
	K	-200 to 1372°C	-2000 to 13720		
	J	-200 to 1200°C	-2000 to 12000		
	Т	-200 to 400°C	-2000 to 4000		
	S	-50 to 1768°C	-500 to 17680		
Thermocouple	R	-50 to 1768°C	-500 to 17680	0.1°C	
mermocoupie	Ν	0 to 1300°C	0 to 13000	0.1 0	
	E	-200 to 1000°C	-2000 to 10000		
	В	0 to 1800°C	0 to 18000		
	PL II	0 to 1390°C	0 to 13900		
	W5Re/W26Re	0 to 2300°C	0 to 23000		
		0 to 10mV	0 to 20000	0.5 <i>µ</i> V	
Micro voltage		0 to 100mV	0 10 20000	5 <i>µ</i> V	
Nicro voltage		-10 to 10mV	-10000 to 10000	1 <i>µ</i> V	
		-100 to 100mV	-10000 10 10000	10 <i>µ</i> V	
		0 to 1V		0.05mV	
		1 to 5V	0 to 20000	0.2mV	
		0 to 5V	0 10 20000	0.25mV	
Voltage		0 to 10V		0.5mV	
		-1 to 1V		0.1mV	
		-5 to 5V	-10000 to 10000	0.5mV	
		-10 to 10V]	1mV	
Current		4 to 20mA	0 to 20000	0.8 <i>µ</i> A	
Current		0 to 20mA	0 10 20000 1 µA		

2.3 Indicated Accuracy for Ambient Temperature (1) Ambient temperature 23±2°C

Item		Error		
		Less than -100°C	±1.0°C	
	K,J,T,E,PL II	-100 to less than 500°C	±0.5°C	
		500°C or more	\pm (indicated value×(0.1%)+1digit)	
Thermocouple	S,R,N, W5Re/W26Re	-50 to less than 1000°C	±1.0°C	
mermocoupie		1000°C or more	\pm (indicated value×(0.1%)+1digit)	
	В	Less than 400°C	±70.0°C	
		400 to less than 1000°C	±1.0°C	
		1000°C or more	\pm (indicated value×(0.1%)+1digit)	
Micro voltage		Full-scale×(±0.1%)		
Voltage				
Current				

(2) Ambient temperature 0 to 55°C

Item		Error		
		Less than -100°C	±2.0°C	
	K,J,T,E,PL II	–100 to less than 500°C	±1.0°C	
		500°C or more	\pm (indicated×(0.2%)+1digit)	
Thermocouple	S,R,N, W5Re/W26Re	–50 to less than 1000°C	±2.0°C	
memocoupie		1000°C or more	\pm (indicated × (0.2%)+1 digit)	
	В	Less than 400°C	±140.0°C	
		400 to less than 1000°C	±2.0°C	
		1000°C or more	\pm (indicated × (0.2%)+1 digit)	
Micro voltage				
Voltage		Full-scale $ imes$ (±0.2%)		
Current				

2.4 Operation at Input Disconnection

Input	Input range	Operation
Thermocouple Micro voltage	- All	Up scale *1
	1 to 5V	Down scale *2
Voltage	0 to 1V,-1 to 1V,0 to 5V,-5 to 5V, 0 to 10V,-10 to 10V	Value near 0V is displayed *3
Current	4 to 20mA	Down scale
Current	0 to 20mA	Value near 0mA is displayed *3

*1: "Input range upper limit value + (full scale ×5%)" is displayed)

*2: "Input range lower limit value -(full scale ×5%)" is displayed)

*3: In this case, as the measurement value is within input range, channels not even connected do not occur alarm.

REMARKS

If detection of an error is required, make sure to set the range actually to use so that a value near 0V/0mA is not displayed.

(Example)

When using voltage input of 0 to 5V range, set the input range actually to use to a range of 1 to 4V.

3. LOADING AND INSTALLATION

3.1 Handling Instructions

There are the following instructions for handling the Q62HLC.

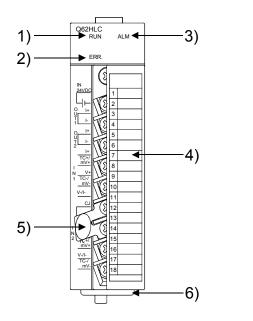
- (1) Do not drop the case and connectors of the module and subject them to hard impact.
- (2) Tighten the module fixing screws and terminal screws of the module within the following ranges.

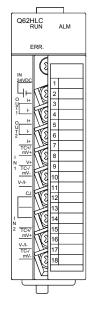
Screw Location	Tightening Torque Range
Module fixing screw (M3 screw)	0.36 to 0.48N•m
Terminal block terminal screw (M3 screw)	0.42 to 0.58N•m
Terminal block mounting screw (M3.5 screw)	0.66 to 0.89N∙m
FG terminal screw (M3 screw)	0.42 to 0.58N•m

3.2 Installation Environment

Refer to the user's manual of the CPU module used.

4. NAMES AND SETTINGS OF THE PARTS





[Condition without temperature compensation resistor]

Number	Name and Appearance	Description	
1)	RUN LED	 Indicates the operating status of the Q62HLC. On : Operating normally. Off : 5V power switched off, a watchdog timer error occurred, or changing online module is allowed. 	
2)	ERR. LED	 Indicates the error status of the Q62HLC. On : Hardware fault (Includes the case of cold junction temperature compensation resistance is not connected) Flicker: Write data error occurrence At auto turning error completion Off : Operating normally. 	
3)	ALM LED	Indicates the alarm status of the Q62HLC. On : Alarm occurrence Flicker: Process value (PV) is outside the measured temperature range. Loop wire break was detected. Sensor is not connected. *1 Off : No alarm occurrence	
4)	Terminal block	Terminal blocks are used for various sensor input, current output and external power supply input.	
5)	Cold junction temperature compensation resistor	Used for Cold junction temperature compensation.	
6)	FG terminal	For frame ground.	

*1: The detection may not be made depending on the input range to use. Refer to Section 2.4 for details.

Terminal Number	Signal Number		Content		
1	24VDC +		24VDC + external power supply for current output		
2	24VDC -		24VDC - external power supply for current output		
3	OUT1	+	CH1	Current output +	
4	0011	 -	СПІ	Current output -	
5	OUT2	+	CH2	Current output +	
6	0012	I-		Current output -	
7	IN1	+		Current input +	
8		TC+/mV+	CH1	Thermocouple/micro voltage input+	
9		V+		Voltage input +	
10		TC-/mV-		Thermocouple/micro voltage input -	
11		V-/I-		Voltage/Current input -	
12	CJ		Cold junctic	Cold junction temperature compensation resistor	
13	IN2	+	CH2	Current input +	
14	CJ		Cold junctic	unction temperature compensation resistor	
15		V+		Voltage input +	
16	IN2	TC+/mV+	CH2	Thermocouple/micro voltage input +	
17		V-/I-		Voltage/Current input -	
18		TC-/mV-		Thermocouple/micro voltage input -	

(1) Terminal number and signal number

5. WIRING

5.1 Wiring Instructions

- (1) Use separate cables for the AC control circuit and Q62HLC's external input output signals to avoid the influence of AC side surges and inductions.
- (2) Do not run the module cables near, or bundle them with, the main circuit and high-voltage cables and the load cables from other than the programmable controller.

Always place the temperature and the micro voltage signal lines more than 100mm (3.94inch) away from the main circuit cables and AC control circuit. Fully keep the sensors away from high-voltage cables and circuits which include high frequencies, e.g. inverter's main load circuit.

Not doing so can make the sensors more susceptible to noises, surges and inductions.

(3) Earth the shielded wire or shielded cable to FG of the programmable controller.

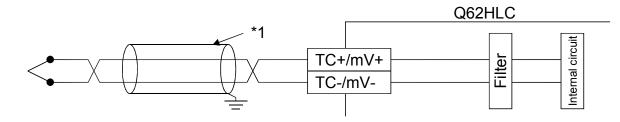
However, depending on the external noise conditions, external earthing may be recommended.

(4) For details on making the wiring conform to the EMC directive and low voltage instruction, please refer to [Conformation to EMC Directive and Low Voltage Instruction] of this manual.

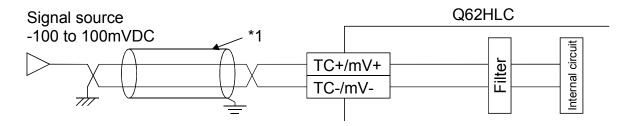
5.2 External Wiring

(1) Input

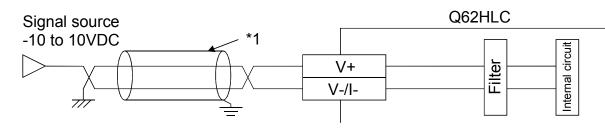
(a) For the thermocouple input



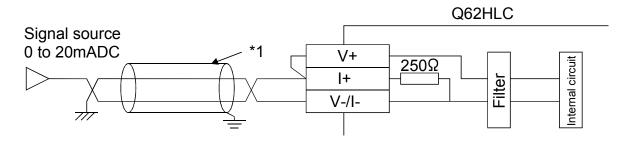
(b) For the micro voltage input



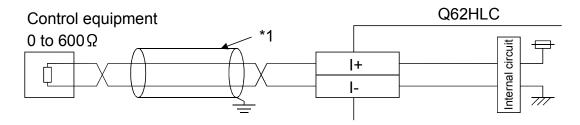
(c) For the voltage input



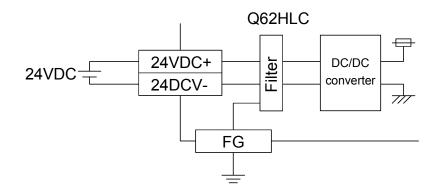
(d) For the current input



(2) Output



(3) External power supply



*1: Always use shielded wires for cables.

6. SETTING FROM GX Developer

The Q62HLC allows you to set the output status at an error stop of the programmable controller CPU by making the intelligent function module switch setting.

Make the intelligent function module switch setting using the I/O assignment setting of GX Developer.

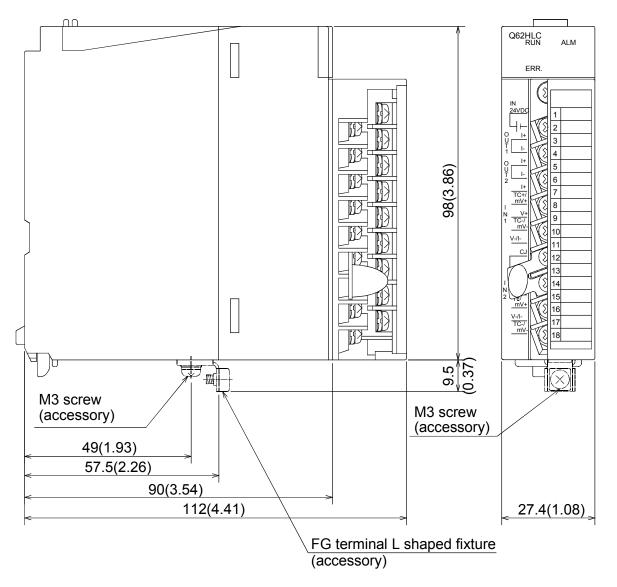
You can make setting easily by entering hexadecimal numbers into 4 digits.

	Setting Item		
Switch 1	CH4 CH3 CH2 CH1	Output setting at CPU stop error 0 : CLEAR Other than 0 : HOLD	
Switch 2 *1	Control status at shifting to program control		
	1 : Shift with executing control		
	Other than 1 : Shift with suspending control		
Switch 3	Use prohibited (0, fixed)		
Switch 4	Use prohibited (0, fixed)		
Switch 5	Use prohibited (0, fixed)		

*1: Compatible with the Q62HLC of which the first five digits of the production information is "10022" or later or the first five digits of the product information is "10011" or later. (For the method of confirming the production information and product information, refer to the Loop Control Module User's Manual.) When using the Q62HLC which is not compatible with this setting, set 0.

If the switches for the intelligent function module are not set, the default value of 0 is used for switches 1 to 5.

7. EXTERNAL DIMENSIONS



Unit: mm (inch)

Warranty

Mitsubishi will not be held liable for damage caused by factors found not to be the cause of Mitsubishi; machine damage or lost profits caused by faults in the Mitsubishi products; damage, secondary damage, accident compensation caused by special factors unpredictable by Mitsubishi; damages to products other than Mitsubishi products; and to other duties.

▲ For safe use

- This product has been manufactured as a general-purpose part for general industries, and has not been designed or manufactured to be incorporated in a device or system used in purposes related to human life.
- Before using the product for special purposes such as nuclear power, electric power, aerospace, medicine or passenger movement vehicles, consult with Mitsubishi.
- This product has been manufactured under strict quality control. However, when installing the product where major accidents or losses could occur if the product fails, install appropriate backup or failsafe functions in the system.

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