



Trajexia motion control system

TJ1-MC04 TJ1-MC16

QUICK START GUIDE



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		······································	
1	1 Introduction		4
	1.1 About this guide		4
	1.2 Overview of this guide		5
	1.3 What you need		6
2	2 From box to rail		7
~	2.1 Pules of a Traievia system		7
	2.1 Rules of a Hajexia System		. / 8
	2.2 Contents of the boxes	······	.0 10
			10
3	3 Connections		3
	3.1 Before work	······	13
	3.2 Power Supply Units	, 	13
	3.2.1 Recommended Power Supply Unit	······	14
	3.2.2 Optional Power Supply Units	······	15
	3.3 TJ1-MC		16
	3.4 TJ1-ML		17
	3.4.1 Attach the MECHAI ROLINK-II Interface	Unit to the Servo Driver	18
	3.4.2 Connect the 200 V single-phase Servo D		19
	3.4.3 Connect the 400 V three-phase Servo Dr	nver	20
	3.4.4 Connect the MSTID		21 つつ
	3.5 Complete installation		22 23
			20
4	4 Trajexia Tools		24
	4.1 Minimum PC configuration	······	24
	4.2 Install the Trajexia Tools software		24
	4.3 Connection to the TJ1-MC		29
	4.4 Create a project for the first time		34
	4.5 Complete installation		42
5	5 More information		13
•	5.1 The Traiexia system		43
	5.2 Traiexia highlights		44
	5.2.1 Direct connectivity via Ethernet		44
	5.2.2 Keep your know-how safe		44
	5.2.3 Serial port and local I/Os		44
	5.2.4 MECHATROLINK-II		44
	5.2.5 TJ1-FL02		44
	5.2.6 Drivers and inverters		45
	5.2.7 Remote I/Os		45

Contents



	5.2.8	PROFIBUS	45
	5.2.9	DeviceNet	45
5.3	Trajexia	a manuals	45



1 Introduction

This Quick Start Guide intends the user to get familiar quickly with the Trajexia system. This Quick Start Guide explains how to get a single axis moving in a simple desktop set-up by the Trajexia system and a Sigma-II Servo Driver by MECHATROLINK-II.

This Quick Start Guide is intended for personnel with knowledge of electrical systems (electrical engineers or equivalent). The engineer has to make sure to operate safely with respect to the power (power supply for Trajexia and power for the Servo Driver, which may be 380 VAC) and moving parts of the motor. When the Trajexia system is used in a real application, the safety warnings and cautions listed in the Hardware Reference Manual must be followed.

For detailed information of the Trajexia system, please refer to the manuals listed in section 5.3.

1.1 About this guide

This Quick Start Guide describes how to connect a Trajexia system to a Sigma-II Servo Driver by MECHATROLINK-II communication. Also the installation of the Trajexia Tools operating software is described, and an example program that controls one servo motor is given.

This Quick Start Guide contains both procedures and descriptive information. Procedure steps that the reader must execute are numbered. All other information is plain text or bulleted text.

Introduction



1.2 Overview of this guide

Chapter 2 describes how to unpack the boxes and install the Trajexia units on a rail.

Chapter 3 describes how to connect a servo motor to the Trajexia system.

Chapter 4 describes how to connect the Trajexia system to a PC and write an example program to operate the servo motor.

fig. 1 fig. 2 fig. 3



1.3 What you need

You need these items for the installation described in this Quick Start Guide.

1.3.1 Trajexia units

- A Power Supply Unit. This can be one of these:
 - CJ1W-PA202.
 - CJ1W-PA205R.
 - CJ1W-PD025.
- A TJ1-MC_ (Motion Controller Unit). This can be one of these:
 - TJ1-MC04.
 - TJ1-MC16.
- A TJ1-ML__ (MECHATROLINK-II Master Unit). This can be one of these:
 - TJ1-ML04.
 - TJ1-ML16.
- A TJ1-TER (Terminator Unit). Supplied together with the TJ1-MC__ unit.

1.3.2 Other units

- A MECHATROLINK-II Interface Unit (NS115).
- A MECHATROLINK-II cable.
- A MECHATROLINK-II terminator.
- A 200 V single-phase Servo Driver or a 400 V three-phase Servo Driver.
- A servo motor.
- A PC.
- The Trajexia Tools software CD-ROM.
- Power and encoder cables from Servo Driver to motor.



2 From box to rail

This chapter describes the actions needed to attach the units to a DIN rail.

2.1 Rules of a Trajexia system

Before you attach the units together, make sure these rules of attachment are followed:

- The first unit on the left is a Power Supply Unit.
- You must attach one TJ1-MC__ to the Power Supply Unit.
- You can attach no more than seven units plus a TJ1-TER to the TJ1-MC___.
- The last unit must be a TJ1-TER.
- You can install up to four TJ1-ML__ units in the system.
- You can install up to seven TJ1-FL02 units (Flexible Axis Unit) in the system with the TJ1-MC16. You can install up to three TJ1-FL02 units in the system with the TJ1-MC04.
- You can install either one TJ1-PRT (PROFIBUS-DP Slave Unit) or one TJ1-DRT (DeviceNet Slave Unit) in the system.
- You can fit the units between the TJ1-MC__ and the TJ1-TER in any order.

Do not change the positions of the units after programs have been written. Programs can become invalid.



2.2 Contents of the boxes

This section lists the Trajexia units you need for the installation.

2.2.1 Power Supply Unit

The box of the Power Supply Unit contains:

- Safety sheet.
- Power Supply Unit.
- Protection label attached to the top surface of the unit.

2.2.2 TJ1-MC___

The box of the TJ1-MC__ contains:

- Safety sheet.
- TJ1-MC__.
- Protection label attached to the top surface of the TJ1-MC___.
- TJ1-TER, attached to the TJ1-MC__.
- Parts for a serial connector.
- Parts for an I/O connector.
- Two metal DIN-rail clips, to prevent the Trajexia system from sliding off the rail.
- White clip, to replace the yellow clip of the Power Supply Unit.

2.2.3 TJ1-ML___

The box of the TJ1-ML__ contains:

- Safety sheet.
- TJ1-ML___.
- Protection label attached to the top surface of the unit.

2.2.4 Software

The software box contains:

- Trajexia Tools CD-ROM.
- Label with the software licence number, attached to the CD jewel case.
- Warranty Registration Form card.

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- Address labels.
- Licence envelope.



2.3 Install the Trajexia system

- 1. Remove all the units from the packaging. Make sure all units are complete.
- 2. Do not remove the protection labels from the units.
- To disconnect the TJ1-MC__ and the TJ1-TER, push the clips (A) on top and bottom of the TJ1-TER to the front.
- 4. Disconnect the TJ1-TER from the TJ1-MC___.

5. Push the clips (A) on top and bottom of all the units to the front.





6. Attach the TJ1-MC__ (C) to the Power Supply Unit (B).

7. Push the clips (A) on top and bottom to the rear.



- 8. Repeat the previous two steps for all other units.
- 9. Make sure the last unit is the TJ1-TER.

10. Pull down all the clips (D) on all units.

- 11. Attach the Trajexia system to the DIN rail.
- 12. Push all the clips (D) up on all units.



3 Connections

This chapter describes the connections of the Trajexia units.

3.1 Before work

In this desktop environment the emergency stops, interlock circuits and limit switches are not installed.



Caution

The electrical engineer has to make sure to operate safely with respect to the power (power supply for Trajexia and power for the Servo Driver, which may be 380 VAC) and moving parts of the motor.

3.2 Power Supply Units

You can use three different types of Power Supply Unit:

Power Supply Unit	Current	Input voltage	Operating voltage limits	Operating frequency limits	Output power
CJ1W-PA202	AC	110 - 240 V	85 - 264 V	47 - 63 Hz	14 W
CJ1W-PA205R	AC	110 - 240 V	85 - 264 V	47 - 63 Hz	25 W
CJ1W-PD025	DC	24 V	21.6 - 26.4 V	N/A	25 W

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3.2.1 Recommended Power Supply Unit

The recommended Power Supply Unit is the CJ1W-PA202.

1. Connect the CJ1W-PA202 Power Supply Unit as follows:

Terminal	Description	Connection
A	110 - 240 V power supply	Live VAC
В	110 - 240 V power supply	Live VAC
С	Line earth	Short-circuit to terminal D
D	Earth	Short-circuit to terminal CEarth





3.2.2 Optional Power Supply Units

1. Connect the CJ1W-PA205R Power Supply Unit as follows:

Terminal	Description	Connection
A	110 - 240 V power supply	Live VAC
В	110 - 240 V power supply	Live VAC
С	Line earth	Short-circuit to terminal D
D	Earth	Short-circuit to terminal CEarth

1. Connect the CJ1W-PD025 Power Supply Unit as follows:

Terminal	Description	Connection
A	24 V power supply	24 VDC
В	0 V power supply	0 V
С	Line earth	Short-circuit to terminal D
D	Earth	Short-circuit to terminal CEarth



3.3 TJ1-MC___

3.3.1 Ethernet port

If you set the power of the Trajexia system on, the three-digit LED display (A) shows the IP address and the subnet mask of the TJ1-MC__.

Use the Ethernet port (B) to connect the TJ1-MC__ to a PC. You can use both a crossover and a patch Ethernet cable. If you connect the PC directly to the TJ1-MC__, and not via a hub or any other network device, the PC must have a fixed IP address. The TJ1-MC automatically detects when you insert an Ethernet

cable into the Ethernet port. When you insert an Ethernet cable into the Ethernet port, the LED display (A) shows the IP address of the TJ1-MC__.

3.3.2 Serial port

The serial port (D) is used to connect the TJ1-MC___ to a device that needs serial connection. It is described in the Hardware Reference Manual. You do not need this port in the example installation.

3.3.3 28-Pin I/O port

The 28-pin I/O port (C) contains 16 digital inputs and 8 digital outputs. It is described in the Hardware Reference Manual. You do not need this port in the example installation.



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3.4 TJ1-ML___

The TJ1-ML___ is the master of a number of MECHATROLINK-II devices. MECHATROLINK-II devices are Servo Drivers, I/Os or inverters. I/Os and inverters are described in the Hardware Reference Manual.

The TJ1-ML__ has one port (A) to connect it to the first MECHATROLINK-II device.







3.4.1 Attach the MECHATROLINK-II Interface Unit to the Servo Driver

You can use a 200 V single-phase Servo Driver (see page 19) or a 400 V three-phase Servo Driver (see page 20).

- 1. Insert the clips (A) of the MECHATROLINK-II Interface Unit (NS115) into the openings (B) of the Servo Driver.
- 2. Make sure the port (C) of the Servo Driver is located opposite to the slot of the NS115.
- 3. Insert the clip (D) of the NS115 into the opening (E) of the Servo Driver.

4. Connect the earth wire (F) of the NS115 to the point marked **G** (G) on the Servo Driver.







3.4.2 Connect the 200 V single-phase Servo Driver

1. The terminals in group A are for the mains supply input that is used to generate power output to the motor (group C). Connect the terminals as follows:

Terminal	Description	Connection
D, E	200 - 230 V power supply	Live VAC
F	+DC bus 1	Short-circuit to terminal G
G	+DC bus 2	Short-circuit to terminal F

 The terminals in group B are for the mains supply input for the internal power needs of the Servo Driver (display, LEDs). Connect the terminals as follows:

Terminal	Description	Connection
Н	200 - 230 V control supply	Live VAC
I	200 - 230 V control supply	Live VAC

3. The terminals in group C are terminals for the power output to the motor. Connect the terminals as follows:

Terminal	Description	Connection
U	Motor phase U	The U terminal on the motor
V	Motor phase V	The V terminal on the motor
W	Motor phase W	The W terminal on the motor

4. Connect the encoder input port (J) to the servo motor encoder cable.





3.4.3 Connect the 400 V three-phase Servo Driver

1. The terminals in group A are for the mains supply input that is used to generate power output to the motor (group C). Connect the terminals as follows:

Terminal	Description	Connection
D, E, F	400 V three-phase power supply	Live VAC
G	+DC bus 1	Short-circuit to terminal H
Н	+DC bus 2	Short-circuit to terminal G

2. The terminals in group B are for the mains supply input for the internal power needs of the Servo Driver (display, LEDs). Connect the terminals as follows:

Terminal	Description	Connection
I	Control supply	24 VDC
J	Control supply	0 VDC
к	Common for regenerative resistance	Short-circuit to terminal L ¹
L	Internal regenerative resistance	Short-circuit to terminal K

1. If the internal resistor is used.

3. The terminals in group C are terminals for the power output to the motor. Connect the terminals as follows:

Terminal	Description	Connection
U	Motor phase U	The U terminal on the motor
V	Motor phase V	The V terminal on the motor
W	Motor phase W	The W terminal on the motor

4. Connect the encoder input port (M) to the servo motor encoder cable.





3.4.4 Connect the NS115

The NS115 has one dipswitch, one address selector, and two MECHATROLINK-II bus ports.

Port or switch	Description		
A	Address selector		
В	Dipswitch		
С	MECHATROLINK-II bus ports		

- 1. Connect a MECHATROLINK-II cable (E) to the TJ1-ML__ (D) and to one of the bus ports of the NS115.
- 2. Connect a MECHATROLINK-II terminator (F) to the other bus port of the NS115.









3.4.5 Set the dipswitches and address of the NS115

The dipswitches on the NS115 configure its communication settings.

1. Set the dipswitches as follows:

Dipswitch	Function	Setting	Description	
1	Baud rate	ON	10 Mbps	
2	Data length	ON	32-byte data transmission	
3	Address range	OFF	Addresses 40-4F	
4	Maintenance (Reserved)	OFF	Must always be set to OFF. ON is not used	

2. Set the address selector of the NS115 to 1. This assigns logical address 41 to the Servo Driver.









3.5 Complete installation

The complete installation of this example consists of a Power Supply Unit (A), a TJ1-MC__ (B), a TJ1-ML__ (C), a Servo Driver (D), an NS115 (E), a motor (F) and a TJ1-TER (G). You can now remove the protection labels from the units.



Trajexia Tools

4 Trajexia Tools

4.1 Minimum PC configuration

You need a PC with this minimum configuration to install Trajexia Tools:

- Windows 98 SE.
- 300 MHz Pentium CPU.
- 64 MB RAM.
- 140 MB hard disk space.
- An Ethernet port.
- If your operating system is Windows 98 SE or Windows ME: Internet Explorer 5.0.
- If your operating system is Windows 2000 or Windows XP: Internet Explorer 6.0.

4.2 Install the Trajexia Tools software

- 1. Insert the Trajexia Tools CD into the CD-ROM drive of the PC.
- 2. The Trajexia Tools Setup program starts automatically.
- 3. If the Trajexia Tools Setup program does not start automatically, start it manually: execute **setup.exe** in the root directory of the CD.
- 4. Select the language you want to use from the drop-down list. Click **OK**.

Choose Setup Language	
Select the language for this installation from the choices below.	
English	
Cancel	
	Choose Setup Language Select the language for this installation from the choices below. English OK Cancel

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Trajexia Tools

5. The Trajexia Tools Setup window shows. Click Next.

6. Click **Yes** to accept the licence agreement and continue.

fig. 2 TrajeXia Tools v1.0 Setup Welcome to the InstallShield Wizard for TrajexiaTools trajexia The InstallShield® Wizard will install TrajexiaTools on your computer. To continue, click Next. Next > Cancel fig. 3 TrajeXia Tools v1.0 Setup License Agreement trajexia Please read the following license agreement carefully. Press the PAGE DOWN key to see the rest of the agreement. **IMPORTANT** ^ By installing this package, you agree to be bound by the following Software License Agreement. If you do not agree, please return the enclosed software ("Software") without installing this package to the shop where you bought the Software. The warranty service set forth in Section 7 of the Software License Agreement and any information on the Software and its revision and new version will not be provided to you, unless you register as an user of the Software by the enclosed user registration card. Please promptly fill in the card and send it to DMRON Corporation. v Do you accept all the terms of the preceding License Agreement? If you select No, the setup will close. To install TrajexiaTools, you must accept this <u>Print</u> agreement. < <u>B</u>ack Yes No

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8. Type your company name in the Company field. 9. Type your user licence number in the Licence fields. Your user

7. Type your name in the Name field.

- licence number is on the label attached to the jewel case of the Trajexia Tools CD.
- 10. Click Next.

Trajexia Tools

11. Click Yes.

12. Click Next.

User Information Enter your registration information. Please enter your name, the name of the company for whom you work and the product licence number shown on the CD case.

Your name

fig. 4

Setup

Manag

		,				
	<u>C</u> ompany:	Your company				
	Licence:					
	Omron —					
		< <u>B</u> ack <u>N</u> ext > Cancel				
L						
fig.	5					
Ľ						
		Registration Confirmation				
1						
		You have provided the following registration information:				
		Name: Your name				
1		Company: Your company				
		Serial Number: xxxx-xxxx-xxxx				
		Is this registration information correct?				
		Yes No				
fin	6					
g.	<u> </u>					
	TrajeXia Tool	ls v1.0 Setup				
	Select Featu	ures e				
1	Select the fe	eatures setup will install. trajexia				
1	Salact the fe	adures you want to install, and develoci the features you do not want to install				
	Select the fe	successed want to install, and deselect the reactives you do not want to install.				
		Dive Description				
	Drive	erver CV Determined and CV Det				
	Trajexia Tools					
	WinMerge					
1						
1	129.03 MB o	of space required on the C drive				
	31634.47 ME	B of space available on the C drive				
	InstallShield					
		< <u>B</u> ack <u>N</u> ext > Cancel				



<u>trajexia</u>

13. Click Next.

14. Click Next.

Choose Destination Location	
Select folder where setup will install files.	trajexia
Setup will install TrajexiaTools in the following	folder.
To install to this folder, click Next. To install to another folder.	a different folder, click Browse and select
Destination Folder	
C:\Program Files\OMRON\	Browse
stallShield	
	< Back Next> Cancel
- L.V. T. L. d. O.F. Aug	
rajeXia Tools v1.0 Setup Select Preuvo Eckler	
rajeXia Tools v1.0 Setup Select Program Folder Please select a program folder.	trajexia
rajeXia Tools v1.0 Setup Select Program Folder Please select a program folder. OMRON	trajexia
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rajeXia Tools v1.0 Setup Select Program Folder Please select a program folder. OMRON Program Folder: IOMRON	trajexti
rajeXia Tools v1.0 Setup Select Program Folder Please select a program folder. OMRON Program Folder: OMRON Existing Folders:	trajexti
rajeXia Tools v1.0 Setup Select Program Folder Please select a program folder. OMRON Program Folder: <u>IOMRON</u> Existing Folders: Accessories	trajexti
rajeXia Tools v1.0 Setup Select Program Folder Please select a program folder. OMRON Program Folder: IMRON Existing Folders: Accessories Startup	trajexti
rajeXia Tools v1.0 Setup Select Program Folder Please select a program folder. OMRON Program Folder: [OMRON] Existing Folder: Accessories Startup	trajexti
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rajeXia Tools v1.0 Setup Select Program Folder Please select a program folder. DMRDN Program Folder: IMRCN Existing Folders: Accessories Startup	trajoxía

QUICK START GUIDE

Trajexia Tools

17. Click **Finish**. The CX-Drive Readme File window shows. Close this window.



Finish

Trajexia Tools



4.3 Connection to the TJ1-MC___

You need a patch or crossover Ethernet cable to connect the PC to the TJ1-MC___.

- 1. Connect the Trajexia system to the mains power supply.
- The IP address and subnet mask of the TJ1-MC__ show 3 times in the LED display (A). The default IP address of the TJ1-MC__ is 192.168.0.250. The default subnet mask is 255.255.255.0.
- 3. If you need to see the IP address and the subnet mask of the TJ1-MC__ again, set the power of the Trajexia system off and then again on.
- 4. Connect the Ethernet cable to the Ethernet port of the PC.
- 5. Connect the Ethernet cable to the Ethernet port of the TJ1-MC__. The IP address of the TJ1-MC__ shows 4 times in the LED display.



Trajexia Tools

- 6. Start the Trajexia Tools program on your PC. Select from the Windows **Start** menu:
- Programs
- OMRON
- Trajexia Tools
- Trajexia Tools
- 7. The **Motion Perfect 2** start-up screen shows. Wait until the **Cancel** button is visible. Then click **Cancel**.

- 8. Select the menu:
- Options
- Communications



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- 9. Make sure ENet0 in the list is selected.
- 10. Click Configure.

11. Type **192.168.0.250** in the **Server name/IP address** field. 12. Click **OK**.

13. Click **OK**.



Trajexia Tools

- 14. Open the Windows Control Panel on your PC.
- 15. Double-click on the Network Connections icon.
- 16. Right-click on the Local Area Connection icon. Click on the **Properties** menu.

- 17. Click on the General tab.
- 18. Select Internet Protocol (TCP/IP) in the list.
- 19. Click Properties.



Transmission Control Protocol/Internet Protocol. The default
wide area network protocol that provides communication
across diverse interconnected networks.

Show icon in notification area when connected
Notify me when this connection has limited or no connectivity

Install... Description traje

Properties

Cancel

OK

Trajexia Tools

- 20. Click on the **General** tab.
- 21. Select Use the following IP address.
- 22. Type 192.168.0.251 address in the IP address field.
- 23. Type 255.255.255.0 in the Subnet mask field.
- 24. Click **OK**.
- 25. Click **OK**.
- 26. Close the Network Connections screen.



neral	
ou can get IP settings assigner s capability. Otherwise, you ne e appropriate IP settings.	d automatically if your network support sed to ask your network administrator f
Obtain an IP address autor	matically
Use the following IP addres	22:
IP address:	192.168.0.251
S <u>u</u> bnet mask:	255 . 255 . 255 . 0
Default gateway:	
) O <u>b</u> tain DNS server addres:	s automatically
Use the following DNS ser	ver addresses:
Preferred DNS server:	
Alternate DNS server:	
	Advanced

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4.4 Create a project for the first time

- 1. Set the power of the Trajexia system and the Servo Driver and NS115 off.
- 2. Set the power of the Servo Driver and NS115 on.
- 3. Set the power of the Trajexia system on.
- 4. Go to the Motion Perfect 2 program on your PC.
- 5. Select the menu:
- Controller
- Connect



7. Click New.

6. Wait until the **OK** button is visible. Then click **OK**.

fig. 21



<u>trajexia</u>

C:\Documents and Setting	gs\\Untitled\Untitle	d. prj
Controller	Project	
ig TJ1-MC16@ENet0		
* Reading controller directory * Looking for current project * Checking project file C:\Documents Documents\Untitled\Untitled.prj	and Settings\m.weijs	\My
Messages:		
Project file C:\Documents and Setti	ings\m.weijs\My	Save
Documents/Untitled/Untitled.prj no	t found	Load
Save controller programs to new pro	iject	Change
Change project for comparison		- Juligo
Erase controller programs and create	e a new project	New
		Canad

Trajexia Tools

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8. Click Yes.



- 10. Type a name for the new project in the **Project name** field.
- 11. Click Create.









12. Click **OK**.

fig. 25 Check project C:\Program Files\..\Trajexia\Project01\Project01.prj Controller Project TJ1-MC16@ENet0 TJ1-MC16@ENet0 * Calculating controller program checksums * Calculating project program checksums * Cross-checking controller and project programs * Project check completed ^ ~ Messages: Project checked OK fig. 26 ⊢A G Motion Perfect 2 Project Controller Pr gram Tools External Options Window Help - 🗶 🔳 🖫 🛄 🖼 🗟 🛢 📑 🗐 🕀 🐷 🥭 🥔 Controller status C Fixed @ Editable Drives Enabled Run Program OK Selected Program 🕨 🗊 🔳 🛃 🕨 Free Memory: 505354 Motion Stop ų,

TJ1-MC16 ENet0:192.168.0.250

Ready

13. Click the Intelligent drives button (A) on the tool bar.

C:\..\Project01\Project01.prj

14. Click the **Config** button.



Mechatrolink



fig. 27

Drive ID: SGDH-01AE-OY Firmware Version: 0042 Motor ID: SGMAH-01AAA61D-OY Drive Status Drive I/O Prive Status Øutput Completed Forward Inhibit EXT 3 Warning Torque Limit Forward Inhibit EXT 3 Verset Latch Completed Forward Inhibit EXT 3 Servo On If In Range / Speed Limit Honing Docel Encoder Phase A Machine Lock Reverse Soft Limit Encoder Phase C 10 12 Machine Lock Reverse Soft Limit EXT 1 10 12 Verset Axis Type Mechatrolink Speed Drive Monitor APO5 Drive Clear Orive Mode Run Commission Launch Drive Reset Drive Reset	Mechatroli Status Confi	nk Drive SGDH-01AE-OY (Address 0x41 , Axis 0)
Drive Status Drive Status Alarm Voutput Completed Warning Torque Limit Power On Insange / Speed Limit Machine Lock Reverse Soft Limit Machine Lock Reverse Soft Limit Axis Type Mechatrolink Speed Drive Mode Drive Monitor Axis Type Mechatrolink Speed	Drive ID: Motor ID:	SGDH-01AE-OY Firmware Version: 0042 SGMAH-01AAA61D-OY
Axis Type Mechatrolink Speed Drive Monitor APO5 Drive Clear Drive Mode C Run C Commission Drive Reset Drive Reset	Drive Statu: Alarm Warnin Ready Servo Power Machin Home F	Image: Speed Limit Image: Speed Limit On Forward Soft Limit Concorr Speed Image: Speed Limit Drive I/O Forward Inhibit Image: Speed Limit Forward Inhibit Drive I/O Image: Speed Limit Drive I/O Image: Speed Limit Drive I/O Image: Speed Limit Drive I/O Drive I/O Porvard Inhibit Drive I/O Drive I/O Drive I/O Porvard Inhibit Drive I/O Drive I/O
	Axis Type Drive Mode I Run	Mechatrolink Speed Drive Monitor APO5 Drive Clear Commission Drive Reset

- 15. Wait until the **MECHATROLINK Drive SGDH-01AE-OY** window shows.
- 16. Click on the **Configuration** tab.

Trajexia Tools

- 17. Scroll to the row in the list where the value of the **Index** column is **Pn50A.3**.
- 18. In this row, click on the item in the **Value** column. A drop-down list shows.
- 19. Select the value 8:Sets signal OFF. in the drop-down list.
- 20. Press the **Enter** key. The icon in the first column of the row is now red, to indicate that you have changed the setting of this row.

- 21. Scroll to the row in the list where the value of the **Index** column is **Pn50B.0**.
- 22. In this row, click on the item in the **Value** column. A drop-down list shows.
- 23. Select the value 8:Sets signal OFF. in the drop-down list.
- 24. Press the **Enter** key. The icon in the first column of the row is now red, to indicate that you have changed the setting in this row.
- 25. Click the **Download to Drive** button (A).
- 26. Click Close.

τ	D	3 POT Sign	al Manning
I			
2 6	Po50A 2	P-CON Signal Manning (P control when I	8:Sets signal OFF
2	Pn50A.3	P-OT Signal Mapping (* Control Million	7:Sets signal ON
2	Po50B.0	N-OT Signal Mapping	Planute from SIO(Chil 40) innu
2 0	Po50B 1	/ALM-RST Signal Manning (Alarm reset	1:Ipputs from SII(CN1-40) input
2 0	Pn50B 2	P-CL Signal Mapping (Torque control wh	2:Inputs from SI2(CN1-42) input
2 0	Pn50B 3	/N-CL Signal Mapping (Torque control w	3:Inputs from SI3(CN1-43) inpu
2 0	Do50C 0	CDD D Signal Manning (Internal Sat Sna	4:Inputs from SI4(CN1-44) inpu
<			5:Inputs from SI5(CN1-45) inpu
Filter			5:Inputs from SI6(CN1-46) inpu 7:Sete eignel Obl
	A A	Category All	3: Sets signal OFE
	•••		9:Inputs rev. signal from SI0(Cf
			A Inputs revisional from SI1(C
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27. Click Close.



	🚡 Mechatrolink				X	
	Unit 0	••••••••••••••••••••••••••••••••••••••				
	Address:	0x41				
	Model: St	U SDH-				
	Version:	AD11				
	Ŀ	Config				
			[Close	Modify STARTUP program	
fi	л 31					-
ц	j. 0 i					

Axes have changed. Do you want to save changes in STARTUP program?

No

Mechatrolink Drive

<u>Y</u>es

- 28. Click Yes.
- 29. Set the power of the Trajexia system and the Servo Driver off to make the driver settings effective.
- 30. Set the power of the Servo Driver and NS115 on.
- 31. Set the power of the Trajexia system on.

32. Select the menu:

- Program
- New

- 33. Enter a name for the new program in the **Enter new program name** field.
- 34. Click **OK**.









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Trajexia Tools

35. Select the Edit window.
36. Type this example program in the edit window:
BASE(0)
SERVO=ON
WDOG=ON
Ioop: MOVE(10000)
WAIT IDLE
WA(1000)
GOTO loop
37. Click the Run button (A) on the tool bar.



Note:

The default parameters are suitable for use with 13-bit encoders. If the example program does not work, do these steps:

- 38. Check the motor specification or the motor manual for information on the encoder type.
- 39. If the motor has a higher resolution, decrease the value of the parameter P_GAIN and increase the values of the parameters SPEED, ACCEL and DECEL. See the Programming Manual.
 40. Due the gramma again
- 40. Run the example program again.

4.5 Complete installation

Congratulations. You are successful in the completion of this guide. You now have a Power Supply Unit, a TJ1-MC__ and a TJ1-ML__ that is connected to a servo motor, and an example program to control the servo motor. fig. 34

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5 More information

5.1 The Trajexia system

Trajexia is OMRON's motion platform that offers you the performance and the ease of use of a dedicated motion system.

Trajexia is a stand-alone modular system that allows maximum flexibility and scalability. At the heart of Trajexia lies the TJ1 multitasking motion coordinator. Powered by a 32-bit DSP, it can do motion tasks such as e-cam, e-gearbox, registration control and interpolation, all via simple motion commands.

Trajexia offers control of up to 16 axes over a MECHATROLINK-II motion bus or traditional analogue or pulse control with independent position, speed or torque control for every axis. And its powerful motion instruction set makes programming intuitive and easy.

You can select from a wide choice of best-in-class rotary, linear and direct-driver servos as well as inverters. The system is scalable up to 16 axes and 8 inverters & I/O modules.





5.2 Trajexia highlights

5.2.1 Direct connectivity via Ethernet

Trajexia's Ethernet built-in port provides direct and fast connectivity to PCs, PLCs, HMIs and other devices while providing full access to the drivers over a MECHATROLINK-II motion bus. It allows explicit messaging over Ethernet and through MECHATROLINK-II to provide full transparency down to the actuator level, and making remote access possible.

5.2.2 Keep your know-how safe

Trajexia's encryption method guarantees complete protection and confidentiality for your valuable know-how.

5.2.3 Serial port and local I/Os

A serial port provides direct connectivity with any OMRON PLC, HMI or any other field device. 16 Inputs and 8 outputs are freely configurable embedded I/Os in the controller to enable you to tailor Trajexia to your machine design.

5.2.4 MECHATROLINK-II

The TJ1-ML_____ performs control of up to 16 Servo Drivers, inverters or I/Os while allowing complete transparency across the whole system. MECHATROLINK-II offers the communication speed and time accuracy essential to guarantee perfect motion control of Servo Drivers. The motion cycle time is selectable between 0.5 ms, 1 ms or 2 ms.

5.2.5 TJ1-FL02

The TJ1-FL02 is an analogue control unit. It controls up to two axes in these modes:



- · Analogue speed reference plus encoder feedback.
- Encoder input, pulse or absolute.
- Pulse output.

You can connect any Servo Driver to the TJ1-FL02.

5.2.6 Drivers and inverters

A wide choice of rotary, linear and direct-driver servos as well as inverters are available to fit your needs in compactness, performance and reliability. The inverters connected to the MECHATROLINK-II are driven at the same update cycle time as the Servo Drivers.

5.2.7 Remote I/Os

The I/Os on the MECHATROLINK-II motion bus provide for system expansion while keeping the devices under one motion bus.

5.2.8 PROFIBUS

The TJ1-PRT is an interface between the Trajexia system and a PROFIBUS network.

5.2.9 DeviceNet

The TJ1-DRT is an interface between the Trajexia system and a DeviceNet network.

5.3 Trajexia manuals

All the information about the Trajexia system is described in these manuals:

Name	Cat. No.	Contents
Trajexia motion control system Hardware Reference Manual	151E	Describes the installation and hardware specification of the Trajexia units, and explains the Trajexia system philoso- phy.
Trajexia motion control system Programming Manual	152E	Describes the BASIC com- mands to be used for pro- gramming Trajexia, explains the communication protocols and Trajexia Tools software, gives practical examples and troubleshooting information.



Revision history

A manual revision code shows as a suffix to the catalogue number on the front cover of the manual.

Revision code	Date	Revised content
01	August 2006	Original
02	October 2006	DeviceNet update
03	May 2007	Updated with TJ1-MC04 and TJ1-ML04. Updated with general Trajexia system information and Trajexia highlights.



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Note: Specifications are subject to change.

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