Smart Sensors (High-precision Contact Type) ZX Series (ZX-T)

CE



For the most recent information on models that have been certified for safety standards, refer to your OMRON website.

Ordering Information

Sensors

Sensor Heads

Size	Туре	Sensing distance	Resolution (See note.)	Model
6 dia.	Short type	1 mm	0.1 μm	ZX-TDS01T
	Standard type	4 mm		ZX-TDS04T
	Low measurement type			ZX-TDS04T-L
8 dia.	Standard type	10 mm	0.4 μm	ZX-TDS10T
	Ultra-low-load Type			ZX-TDS10T-L
	Air Lift Type			ZX-TDS10T-V
	Air Lift/Air Push Type			ZX-TDS10T-VL

Note: The resolution refers to the minimum value that can be read when a ZX-TDA 1 Amplifier Unit is connected.

■ Amplifier Units

Appearance	Power supply	Output type	Model
C. Sale	DC	NPN	ZX-TDA11
		PNP	ZX-TDA41

■ Accessories (Order Separately)

Calculating Unit

Appearance	Model
	ZX-CAL2

ZX-series Communications Interface Unit

Appearance	Model
S	ZX-SF11

ZX Series (ZX-T) Smart Sensors (High-precision Contact Type)

SmartMonitor Sensor Setup Tool for Personal Computer Connection

Appearance	Name	Model
	ZX-series Communi- cations Interface Unit	ZX-SF11
CD-ROM	ZX-series Communi- cations Interface Unit + ZX-series Sensor Setup Soft- ware Basic	ZX-SFW11EV3 *1, *2
CD-ROM	ZX-series Sensor Setup Software	ZX-SW11EV3 *1

*1. When using the ZX-TDA11/41 with the SmartMonitor, either the ZX-SFW11EV3 or the ZX-SW11EV3 SmartMonitor must be used. Earlier versions cannot be used.

*2. The ZX-SFW11EV3 SmartMonitor can be used only to set functions and monitor waveforms.

Specifications

Amplifier Units

Item	ZX-TDA11	ZX-TDA41		
Measurement period	1 ms			
Possible average count set- tings (See note 1.)	1, 16, 32, 64, 128, 256, 512, or 1,024			
Linear output (See note 2.)	Current output: 4 to 20 mA/F.S., Max. load resistance:	300 Ω		
	Voltage output: ±4 V (±5 V, 1 to 5 V (See note 3.)), Ou	tput impedance: 100 Ω		
Judgement outputs (3 outputs: HIGH/PASS/ LOW)	NPN open-collector outputs, 30 VDC, 30 mA max. Residual voltage: 1.2 V max.	PNP open-collector outputs, 30 VDC, 30 mA max. Residual voltage: 2 V max.		
Zero reset input, timing in-	ON: Short-circuited with 0-V terminal or 1.5 V or less	ON: Supply voltage short-circuited or supply voltage of		
output hold input	OFF: Open (leakage current: 0.1 mA max.)	OFE: Open (leakage current: 0.1 mA max.)		
Function	 Measurement value display Display reverse Sample hold Self-peak hold Initial reset Judgement output hold input Sensor disconnection detection Zero reset indicator Present value/set v ECO mode Peak hold Self-bottom hold Direct threshold val Timing inputs (A-B) calculations (Zero reset indicator Span adjustment 	alue/output value display - Number of display digit changes - Bottom hold, peak-to-peak hold - Zero reset ue setting - Position teaching - Reset input See note 4.) - (A+B) calculations (See note 4.) - Function lock g - Scale inversion - Warming-up display		
Indicators	Judgement indicators: High (orange), pass (green), low sub-digital display (yellow), power ON (green), zero re	(yellow), 7-segment main digital display (red), 7-segment set (green), enable (green)		
Power supply voltage	12 to 24 VDC ±10%, Ripple (p-p): 10% max.			
Current consumption	140 mA max. (with Sensor connected), For 24-VDC por	wer supply voltage: 140 mA max. (with Sensor connected)		
Ambient temperature	Operating and storage: 0 to 50°C (with no icing or condensation)			
Temperature characteristic	0.03% F.S./°C			
Connection method	Prewired (standard cable length: 2 m)			
Weight (packed state)	Approx. 350 g			
Materials	Case: PBT (polybutylene terephthalate), Cover: Polyca	arbonate		

Note 1. The response speed of the linear output is calculated as the measurement period \times (average count setting + 1).

The response speed of the judgement outputs is calculated as the measurement period × (average count setting + 1).

2. The output can be switched between a current output and voltage output using a switch on the bottom of the Amplifier Unit.

3. Setting is possible via the monitor focus function.

4. A Calculating Unit (ZX-CAL2) is required.

Cables with Connectors on Both Ends (for Extension)*

Cable length	Model	Quantity
1 m	ZX-XC1A	1
4 m	ZX-XC4A	
8 m	ZX-XC8A	
* Robet Cable models	ara alaa ayailahla. Tha	model numbero ere

* Robot Cable models are also available. The model numbers are ZX-XC $\square R.$

Preamplifier Mounting Brackets

-	-	
Appearance	Model	Remarks
Sec. Se	ZX-XBT1	Attached to each Sensor Head
	ZX-XBT2	For DIN track mount- ing

Sensor Heads

Item		ZX-TDS01T	ZX-TDS04T	ZX-TDS04T-L	
Measurement range		1 mm	4 mm		
Maximum actuator	travel distance	Approx. 1.5 mm	Approx. 5 mm		
Resolution (See not	te 1.)	0.1 μm			
Linearity (See note	2.)	0.3% F.S.			
Operating force (Se	e note 3.)	Approx. 0.7 N		Approx. 0.25 N	
Degree of protectio	n (Sensor Head)	IEC60529, IP67		IEC60529, IP54	
Mechanical durabili	ty	10,000,000 operations min.			
Ambient temperature		Operating: 0°C to 50°C (with no icing or condensation) Storage: -15°C to 60°C (with no icing or condensation)			
Ambient humidity		Operating and storage: 35% to 85% (with no icing or condensation)			
Temperature char-	Sensor Head	0.03% F.S./°C			
acteristic (See Preamplifier note 4.)		0.01% F.S./°C			
Weight (packed state)		Approx. 100 g			
Materials Sensor Head		Stainless steel			
	Preamplifier	Polycarbonate			
Accessories		Instruction manual, Preamplifier Mounting Brackets (ZX-XBT1)			

Note 1. The resolution is given as the minimum value that can be read when a ZX-TDA 1 Amplifier Unit is connected. This value is taken 15 minutes after turning ON the power with the average number of operations set to 256. 2. The linearity is given as the error in an ideal straight line displacement output.

3. These figures are representative values that apply for the measurement mid-point, and are for when the provided actuator is used, with the actuator moving downwards. If the actuator moves horizontally or upwards, the operating force will be reduced. Also, if an actuator other than the standard moving downwards. If the actuator moves horizontally or upwards, the operating force will be reduced. Also, if an actuator other than the standard moving downwards. one is used, the operating force will vary with the weight of the actuator itself.

4. These figures are representative values that apply for the mid-point of the measurement range.

■ Sensor (Long-range Type)

Item		ZX-TDS10T	ZX-TDS10T-V	ZX-TDS10T-L	ZX-TDS10T-VL	
Vacuum retract (VR) and air push (AP) compatible		No	VR	No	VR/AP	
Measurement range		10 mm				
Maximum actuator travel distance		10.5 mm				
Resolution (See	notes 1 and 5.)	0.4 μm				
Linearity (See no	tes 2 and 5.)	±0.5% F.S.				
Operating force (See note 3.)	Approx. 0.7 N	Approx. 0.6 N	Approx. 0.065 N	Approx. 0.09 to 1.41 N	
Air pressure	Vacuum retracting		–0.55 to –0.70 (bar)		–0.22 to –0.5 (bar)	
	Air push				0.125 to 2 (bar)	
Degree of	Sensor Head	IP65		IP50		
protection Preamplifier		IP40				
Mechanical durability		10,000,000 operations min.				
Ambient temperature		Operating: 0 to 50°C (with no icing or condensation), Storage: -10 to 60°C (with no icing or condensation)				
Ambient humidity		Operating and storage: 35% to 85% (with no icing or condensation)				
Temperature	Sensor Head	±0.01% F.S./°C				
(See note 4.)	Preamplifier	±0.01% F.S./°C				
Vibration resista	nce	0.35-mm single amplitude at 10 to 55 Hz for 50 min each in the X, Y, and Z directions				
Shock resistance)	150 m/S ² 3 times each in 6 directions (up/down, left/right, and forward/backward)				
Connection meth	od	Prewired connector (2 m from the Sensor Head to the Preamplifier, 0.2 m from the Preamplifier to the connector)				
Weight (packed s	state)	Approx. 100 g				
Materials Sensor Head		Stainless steel				
	Rubber sleeve	Viton None				
Preamplifier Mounting Brackets		Polycarbonate				
		Stainless steel				
Accessories		Instruction manual, Preamplifier Mounting Brackets (ZX-XBT1), Right-angle Adapter (See note 6.)				

Note 1. The resolution indicates the variation (±3 σ) in the linear output (voltage output) when a ZX-TDA□1 Amplifier Unit is connected. This value is taken 30 minutes after turning ON the power with the average number of operations set to 1,024. The minimum value that can be read is 1 µm.

2. The linearity is given as the error in an ideal straight line displacement output.

3. These figures are representative values that apply for the mid-point of the measurement range when the Actuator provided is secured facing downa. These figures are representative values that apply force will be reduced if the Actuator is secured facing horizontally or upward.
- ZX-TDS10T-L and ZX-TDS10T-VL: The actuator can be installed only facing downward.
4. These figures are representative values that apply for the mid-point of the measurement range.

5. These values were measured at an ambient temperature of 23°C.

6. The ZX-TDS10T comes with a Right-angle Adapter.

Output Characteristics Voltage/Current Output

ZX-TDS01T/-TDS04T---/-TDS10T-----



*1: Values for the ZX-TDS04T/-TDS04T-

*2: Values for the ZX-TDS10T/-TDS10T-

I/O Circuit Diagrams

NPN Amplifier Unit: ZX-TDA11



PNP Amplifier Unit: ZX-TDA41



Connectors

Amplifier Unit



Part Names

Sensor Heads





- Note 1. Use a stabilized power supply separate from other devices and power systems for the Amplifier Unit, particularly when high resolution is required.
 - 2. Always wire correctly. Incorrect wiring may damage the Unit. Use a different ground for the linear output from the normal ground.
 - 3. The blue line (0 V) is the 0 V power supply line. The shield wire (linear output GND) is used together with the black line (linear output) to connect the linear output. Wire these lines correctly. Always ground the linear output terminal even when the linear output is not used.

Amplifier Unit ZX-TDA11 ZX-TDA41



Calculating Unit

ZX-CAL2



Options (Actuators)

Мо	del	Type (material)	Screw section	Appearance	Application	Applicable Sensor (See note.)
						ZX-TDS T
D5SN-	TB1	Ball type (steel)	Female screw M2.5 x 0.45	6	Measuring ordinary flat surfaces (stan- dard actuator supplied with the ZX-TDS Series)	\bigcirc
	TB2	Ball type (carbide steel)	Female screw		Measurements where abrasion resistance is critical	(
			ME.0 X 0.40	0	Measured objects: Carbide (HR90) or lower.	\bigcirc
	ТВЗ	Ball type (ruby)	Female screw		Measurements where abrasion resistance is critical	\bigcirc
					Measured objects: Carbide (HR90) or higher.	\bigcirc
	TN1	Needle type (car-	Male screw		Measuring the bottom of grooves and	~
		bide steel)	M2.5 x 0.45		noies	\bigtriangleup
	TF1	Flat (carbide steel)	Male screw		Measuring spherical objects	
			M2.5 x 0.45			\bigtriangleup
	ТА	Conversion Adapt-	Through-hole fe-		Mounting D5SN-TN1/-TF1 or commercial-	
			M2.5 x 0.45	•	Sensors	\bigcirc

Note: \bigcirc Replacement possible \bigtriangleup Cor

ightarrow Conversion Adapter required

Dimensions



Replacing Actuators

Be careful not to damage the rubber boot with pliers or other tools when replacing the actuator.

1. Remove the standard actuator.

- Hold the plunger's D-cut section with radio pliers or a similar tool while removing the actuator.
- If the replacement must be performed by holding the Sensor Head itself, ensure that a torque exceeding 0.15 N·m is not applied. Applying excessive torque may have an adverse affect on plunger operation.



2. Mount the commercial actuator to the Conversion Adapter.

- Tighten the actuator securely, and ensure that there is no looseness.
- If necessary, apply a screw-locking agent. (Recommended: Three-Bond 1401B)



Screw-locking agent required

3. Mount the Conversion Adapter to the plunger.

- Hold the plunger's D-cut section with radio pliers or a similar tool while mounting and securing the Conversion Adapter.
- If the replacement must be performed by holding the Sensor Head itself, ensure that a torque exceeding 0.15 N·m is not applied. Applying excessive torque may have an adverse affect on plunger operation.



Design Precautions

- Conform to the specified ratings and performance. Refer to *Specifications* on page 2 for details.
- Measurements may not be possible or may not be accurate for some materials and shapes.
- The Sensor will be destroyed if the Actuator is pressed too far. Do not use the Actuator past the point where a pressing force alarm (OVER) is displayed.
- Do not remove the rubber boot. Without the rubber boot, foreign matter may enter the Sensor Head, possibly causing the Sensor Head to malfunction.
- Use suitable torque and force when mounting the Sensor.
- The Sensor may be destroyed if excessive force is applied.

Environment

- Do not operate the product in locations subject to flammable or explosive gases.
- In order to ensure safe operation and maintenance, do not install the product in the vicinity of high-voltage devices or power equipment.

<u>Wiring</u>

- Do not use the product at voltages exceeding the rated values. Doing so may result in damage.
- Do not connect the product to an AC power supply or connect the power supply in reverse.
- Do not short-circuit the load for open-collector output.

Correct Use

System Design

Warming Up

After turning ON the power, allow the Smart Sensor to warm up for 15 minutes minimum prior to use.

Measurements

Do not expose the plunger to forces exceeding the limits in the following diagram. Doing so may damage the plunger.

ZX-TDS-Series Sensors



Adjustments

Settings

When setting the threshold value with the Smart Sensor connected to an external device, turn ON the Amplifier Unit's judgement output hold input to prevent the judgement from being output to the external device.

Compatibility

Sensors and Amplifier Units are mutually compatible. Sensors can be added or replaced individually.

Influence of High-frequency Electromagnetic Fields

Using the product in the vicinity of devices that generate high-frequency electromagnetic fields, such as ultrasonic cleaning equipment, high-frequency generators, transceivers, mobile phones, and inverters, may result in malfunction.

Other Precautions

Do not attempt to disassemble, repair, or modify the product.

Dispose of the product using standard procedures for industrial waste.

These Sensors are not compatible with the ZX-L \Box Smart Sensors (laser type). Do not connect combinations of ZX-E \Box Smart Sensors and ZX-T \Box Smart Sensors.

<u>Wiring</u>

• Wiring Check

After wiring is completed, before turning ON the power, confirm that the power supply is connected correctly, that there are no faulty connections, such as load short-circuits, and that the load current is correct. Incorrect wiring may result in failure.

Cable Extension

Do not extend the cable for the Sensor and the Amplifier Unit to a length exceeding 10 m. Use a ZX-XC \Box A Extension Cable (sold separately) to extend the Sensor's cable. Extend the Amplifier Unit's cable using a shielded cable of the same type.

Power Supply

When using a commercially available switching regulator, ground the FG (frame ground) terminal.

If the power supply line is subject to surges, connect a surge absorber that meets the conditions of the operating environment.

Dimensions

Sensors

ZX-TDS01T



ZX Series (ZX-T) Smart Sensors (High-precision Contact Type)



Amplifier Unit



■ Accessories (Order Separately)

Preamplifier Mounting Bracket (Supplied with Each Sensor)

ZX-XBT1

ZX-XBT2 (For DIN Track Mounting)



This document provides information mainly for selecting suitable models. Please read the document E346 carefully for information that the user must understand and accept before purchase, including information on warranty, limitations of liability, and precautions.

> ALL DIMENSIONS SHOWN ARE IN MILLIMETERS. To convert millimeters into inches, multiply by 0.03937. To convert grams into ounces, multiply by 0.03527.

CSM_1_1_0812 Cat. No. E345-E1-04 In the interest of product improvement, specifications are subject to change without notice.

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