

Flagship PLCs with Built-in Multifunctional Ethernet Port

- Small, Fast, Flexible:

The CJ2 CPU Units inherit and improve CJ1 features while also adding EtherNet/IP as a standard feature for high-speed, high-capacity Ethernet-based networking.



CJ2H-CPU6□-EIP

Features


- High-speed, high-capacity EtherNet/IP is built into every model.
- The CIP communications protocol is supported for direct access to multivendor devices.
- Tag memory provided for easy access from host PCs and PTs.
- Even more program memory and data memory.
- Superior high-speed control performance: LOAD instructions execute in 16 ns, SINE instructions in 0.59 μ s.
- The more advanced motion control by the lower cost: Synchronous Unit Operation
- Increased I/O throughput speed by Immediate refreshing instructions with direct processing.

Ordering Information

International Standards

- The standards are abbreviated as follows: U: UL, U1: UL (Class I Division 2 Products for Hazardous Locations), C: CSA, UC: cULus, UC1: cULus (Class I Division 2 Products for Hazardous Locations), CU: cUL, N: NK, L: Lloyd, and CE: EC Directives.
- Contact your OMRON representative for further details and applicable conditions for these standards.

CJ2H (Built-in EtherNet/IP) CPU Units

| Product name | Specifications | | | | Current consumption (A) | | Model | Standards |
|---|---|------------------|---|-------------------------------|-------------------------|------|-----------------------|------------------|
| | I/O capacity/Mountable Units (Expansion Racks) | Program capacity | Data memory capacity | LD instruction execution time | 5 V | 24 V | | |
| CJ2H (Built-in EtherNet/IP) CPU Units  | 2,560 points / 40 Units (3 Expansion Racks max.) | 400K steps | 832K words DM: 32K words EM: 32K words × 25 banks | 0.016 μs | 0.82 * | - | CJ2H-CPU68-EIP | UC1, N, L, CE |
| | | 250K steps | 512K words DM: 32K words EM: 32K words × 15 banks | | | | CJ2H-CPU67-EIP | |
| | | 150K steps | 352K words DM: 32K words EM: 32K words × 10 banks | | | | CJ2H-CPU66-EIP | |
| | | 100K steps | 160K words DM: 32K words EM: 32K words × 4 banks | | | | CJ2H-CPU65-EIP | |
| | | 50K steps | 160K words DM: 32K words EM: 32K words × 4 banks | | | | CJ2H-CPU64-EIP | |

* Add 0.15 A per Adapter when using NT-AL001 RS-232C/RS-422A Adapters.
Add 0.04 A per Adapter when using CJ1W-CIF11 RS-422A Adapters.

Accessories

The following accessories come with CPU Unit:

| Item | Specification |
|--|---|
| Battery | CJ1W-BAT01 |
| End Cover | CJ1W-TER01 (necessary to be mounted at the right end of CPU Rack) |
| End Plate | PFP-M (2 pcs) |
| Serial Port (RS-232C) Connector | Connector set for serial port connection (D-SUB 9-pin male connector) |

General Specifications

| Item | | CJ2H- | | | | |
|-----------------------------|--|--|-----------|-----------|-----------|-----------|
| | | CPU64-EIP | CPU65-EIP | CPU66-EIP | CPU67-EIP | CPU68-EIP |
| Enclosure | | Mounted in a panel | | | | |
| Grounding | | Less than 100 Ω | | | | |
| CPU Rack Dimensions | | 90 mm × 65 mm × 80 mm (H × D × W) | | | | |
| Weight | | 280 g or less | | | | |
| Current Consumption | | 5 VDC, 0.82 A | | | | |
| Use Environment | Ambient Operating Temperature | 0 to 55°C | | | | |
| | Ambient Operating Humidity | 10% to 90% (with no condensation) | | | | |
| | Atmosphere | Must be free from corrosive gases. | | | | |
| | Ambient Storage Temperature | -20 to 70°C (excluding battery) | | | | |
| | Altitude | 2,000 m or less | | | | |
| | Pollution Degree | 2 or less: Conforms to JIS B3502 and IEC 61131-2. | | | | |
| | Noise Immunity | 2 kV on power supply line (Conforms to IEC 61000-4-4.) | | | | |
| | Overvoltage Category | Category II: Conforms to JIS B3502 and IEC 61131-2. | | | | |
| | EMC Immunity Level | Zone B | | | | |
| | Vibration Resistance | Conforms to IEC60068-2-6. 5 to 8.4 Hz with 3.5-mm amplitude, 8.4 to 150 Hz Acceleration of 9.8 m/s ² for 100 min in X, Y, and Z directions (10 sweeps of 10 min each = 100 min total) | | | | |
| Shock Resistance | Conforms to IEC60068-2-27. 147 m/s ² , 3 times in X, Y, and Z directions (100 m/s ² for Relay Output Units) | | | | | |
| Battery | Life | 5 years at 25°C | | | | |
| | Model | CJ1W-BAT01 | | | | |
| Applicable Standards | | Conforms to cULus, NK, LR and EC Directives. | | | | |

Performance Specifications

| Items | | CJ2H- | | | | | |
|-------------------------------------|-------------------------------|---|--|----------------------------|-----------------------------|-----------------------------|-----------------------------|
| | | CPU64-EIP | CPU65-EIP | CPU66-EIP | CPU67-EIP | CPU68-EIP | |
| User Memory | | 50K steps | 100K steps | 150K steps | 250K steps | 400K steps | |
| I/O Bits | | 2,560 bits | | | | | |
| Processing Speed | Overhead Processing Time | | Normal Mode: 200 μ s (If tag data links are used with EtherNet/IP, add the following to the above time: 100 μ s + Number of transferred words \times (0.33 μ s or 0.87 μ s *)) * When High-speed interrupt function is used | | | | |
| | Execution Time | | Basic Instructions: 0.016 μ s min.; Special Instructions: 0.048 μ s min. | | | | |
| | Interrupts | I/O Interrupts and External Interrupts | Interrupt task startup time : 26 μ s or 17 μ s * (30 μ s in unit Ver.1.0) Return time to cyclic task : 11 μ s or 8 μ s * (15 μ s in unit Ver.1.0) * When High-speed interrupt function is used | | | | |
| | | Scheduled Interrupts | Interrupt task startup time : 22 μ s or 13 μ s * (27 μ s in unit Ver.1.0) Return time to cyclic task : 11 μ s or 8 μ s * (15 μ s in unit Ver.1.0) * When High-speed interrupt function is used | | | | |
| Maximum Number of Connectable Units | | Total per CPU Rack or Expansion Rack: 10 Units max.; Total per PLC: 40 Units max. | | | | | |
| Maximum Number of Expansion Racks | | 3 max. | | | | | |
| CIO Area | I/O Area | | 2,560 bits (160 words): Words CIO 0000 to CIO 0159 | | | | |
| | Link Area | | 3,200 bits (200 words): Words CIO 1000 to CIO 1199 | | | | |
| | Synchronous Data Refresh Area | | 1,536 bits (96 words): Words CIO 1200 to CIO 1295 | | | | |
| | CPU Bus Unit Area | | 6,400 bits (400 words): Words CIO 1500 to CIO 1899 | | | | |
| | Special I/O Unit Area | | 15,360 bits (960 words): Words CIO 2000 to CIO 2959 | | | | |
| | DeviceNet Area | | 9,600 bits (600 words): Words CIO 3200 to CIO 3799 | | | | |
| | Internal I/O Area | | 3,200 bits (200 words): Words CIO 1300 to CIO 1499 37,504 bits (2,344 words): Words CIO 3800 to CIO 6143 Cannot be used for external I/O. | | | | |
| Work Area | | 8,192 bits (512 words): Words W000 to W511 Cannot be used for external I/O. | | | | | |
| Holding Area | | 8,192 bits (512 words): Words H000 to H511 Bits in this area maintain their ON/OFF status when PLC is turned OFF or operating mode is changed. Words H512 to H1535: These words can be used only for function blocks. They can be used only for function block instances (i.e., they are allocated only for internal variables in function blocks). | | | | | |
| Auxiliary Area | | Read-only: 31,744 bits (1,984 words) • 7,168 bits (448 words): Words A0 to A447 • 24,576 bits (1,536 words): Words A10000 to A11535 * Read/write: 16,384 bits (1,024 words) in words A448 to A1471 * * A960 to A1471 and A10000 to A11535 cannot be accessed by CPU Bus Units, Special I/O Units, PTs, and Support Software that do not specifically support the CJ2 CPU Units. | | | | | |
| Temporary Area | | 16 bits: TR0 to TR15 | | | | | |
| Timer Area | | 4,096 timer numbers (T0000 to T4095 (separate from counters)) | | | | | |
| Counter Area | | 4,096 counter numbers (C0000 to C4095 (separate from timers)) | | | | | |
| DM Area | | 32k words * DM Area words for Special I/O Units: D20000 to D29599 (100 words \times 96 Units) DM Area words for CPU Bus Units: D30000 to D31599 (100 words \times 16 Units) * Bits in the EM Area can be addressed either by bit or by word. These bits cannot be addressed by CPU Bus Units, Special I/O Units, PTs, and Support Software that do not specifically support the CJ2 CPU Units. | | | | | |
| EM Area | | | 32k words/bank \times 25 banks max.: E00_00000 to E18_32767 max. *1 *2 *1. Bits in the EM Area can be addressed either by bit or by word. These bits cannot be addressed by CPU Bus Units, Special I/O Units, PTs, and Support Software that do not specifically support the CJ2 CPU Units. *2. EM banks D to 18 cannot be accessed by CPU Bus Units, Special I/O Units, PTs, and Support Software that do not specifically support the CJ2 CPU Units. *3. Force-set/reset to the EM Area is enabled by specifying a start bank in parameter settings. (unit version 1.2 or higher) | | | | |
| | Force-S/R Enabled Banks | When EM force-S/R function is used *3 | 32K words \times 4 banks | 32K words \times 4 banks | 32K words \times 10 banks | 32K words \times 15 banks | 32K words \times 25 banks |
| | | When automatic address allocation is specified | Bank 0 to 3 | Bank 0 to 3 | Bank 0 to 9 | Bank 0 to E | Bank 0 to 18 |
| | | Bank 3 | Bank 3 | Bank 6 to 9 | Bank 7 to E | Bank 11 to 18 | |
| Index Registers | | IR0 to IR15 These are special registers for storing PLC memory addresses for indirect addressing. (Index Registers can be set so that they are unique in each task or so that they are shared by all tasks.) | | | | | |
| Cyclic Task Flag Area | | 128 flags | | | | | |
| Memory Card | | 128 MB, 256 MB, or 512 MB | | | | | |
| Operating Modes | | PROGRAM Mode: Programs are not executed. Preparations can be executed prior to program execution in this mode. MONITOR Mode: Programs are executed, and some operations, such as online editing, and changes to present values in I/O memory, are enabled in this mode. RUN Mode: Programs are executed. This is the normal operating mode. | | | | | |
| Execution Mode | | Normal Mode | | | | | |

| Items | | CJ2H- | | | | | |
|------------------------------|--|--|---|--------------|--------------|-----------|--|
| | | CPU64-EIP | CPU65-EIP | CPU66-EIP | CPU67-EIP | CPU68-EIP | |
| Programming Languages | | Ladder Logic (LD), Sequential Function Charts (SFC), Structured Text (ST), and Instruction Lists (IL) | | | | | |
| Function Blocks | Maximum number of definitions | 2,048 | | | | | |
| | Maximum number of instances | 2,048 | | | | | |
| Tasks | Type of Tasks | Cyclic tasks Interrupt tasks (Power OFF interrupt tasks, scheduled interrupt tasks, I/O interrupt tasks, and external interrupt tasks) | | | | | |
| | Number of Tasks | Cyclic tasks: 128 Interrupt tasks: 256 (Interrupt tasks can be defined as cyclic tasks to create extra cyclic tasks. Therefore, the total number of cyclic tasks is actually 384 max.) | | | | | |
| Symbols (Variables) | Type of Symbols | <ul style="list-style-type: none"> Local symbols: Can be used only within a single task in the PLC. Global symbols: Can be used in all tasks in the PLC. Network symbols (tags): I/O memory in the CPU Unit can be externally accessed using symbols, depending on parameter settings. | | | | | |
| | Data Type of Symbols | <ul style="list-style-type: none"> BOOL (bit) UINT (one-word unsigned binary) UDINT (two-word unsigned binary) ULINT (four-word unsigned binary) INT (one-word signed binary) DINT (two-word signed binary) LINT (four-word signed binary) UINT BCD (one-word unsigned BCD) *1 UDINT BCD (two-word unsigned BCD) *1 ULINT BCD (four-word unsigned BCD) *1 REAL (two-word floating-point) LREAL (four-word floating-point) CHANNEL (word) *1 NUMBER (constant or number) *1 WORD (one-word hexadecimal) DWORD (two-word hexadecimal) LWORD (four-word hexadecimal) STRING (1 to 255 ASCII characters) TIMER (timer) *2 COUNTER (counter) *2 User defined data types (data structures) *3 <p>*1. Cannot be used in Function blocks *2. Can be used only in Function blocks *3. Supported only when CX-Programmer version 9.0 or later is used</p> | | | | | |
| | Maximum Size of Symbol | 32k words | | | | | |
| | Array Symbols (Array Variables) | One-dimensional arrays | | | | | |
| | Number of Array Elements | 32,000 elements max. | | | | | |
| | Number of Registrable Network Symbols (Tags) | 20,000 max. | | | | | |
| | Length of Network Symbol (Tag) Name | 255 bytes max. | | | | | |
| | Encoding of Network Symbols (Tags) | UTF-8 | | | | | |
| | Data Tracing | Memory Capacity | 8,000 words | 16,000 words | 32,000 words | | |
| | | | (The EM Area can be specified from the CX-Programmer to use up to 32K words multiplied by the number of banks supported by the CPU Unit model.) | | | | |
| Number of Samplings | | Bits = 31, one-word data =16, two-word data = 8, four-word data = 4 | | | | | |
| Sampling Cycle | | 1 to 2,550 ms (Unit: 1 ms) | | | | | |
| Trigger Conditions | | ON/OFF of specified bit Data comparison of specified word Data size: 1 word, 2 words, 4 words Comparison Method: Equals (=), Greater Than (>), Greater Than or Equals (≥), Less Than (<), Less Than or Equals (≤), Not Equal (≠) | | | | | |
| | Delay Value | -32,768 to +32,767 ms | | | | | |
| File Memory | | Memory Card (128, 256, or 512 Mbytes) (Use the Memory Cards provided by OMRON.) EM file memory (Part of the EM Area can be converted for use as file memory.) | | | | | |
| Source/Comment Memory | Program sources, comments, program indexes, symbol tables | Capacity: 3.5 Mbytes | | | | | |

| Item | | CJ2H- | | | | |
|---|----------------------------------|--|--|---|-----------|-----------|
| | | CPU64-EIP | CPU65-EIP | CPU66-EIP | CPU67-EIP | CPU68-EIP |
| Communications | Logical Ports for Communications | Logical Ports | 8 ports (Used for SEND, RECV, CMND, PMCR, TXDU, and RXDU instructions.) | | | |
| | | Extended Logical Ports | 64 ports (Used for SEND2, RECV2, CMND2, and PMCR2 instructions.) | | | |
| | CIP Communications Specification | Class 3 (Connection Type) | Number of connections: 64 | | | |
| | | UCMM (Non-connection Type) | Maximum number of clients that can communicate at the same time: 32 Maximum number of servers that can communicate at the same time: 40 | | | |
| | Peripheral (USB) Port | | USB 2.0-compliant B-type connector | | | |
| | Baud Rate | | 12 Mbps max. | | | |
| | Transmission Distance | | 5 m max. | | | |
| | Serial Port | | Interface: Conforms to EIA RS-232C. | | | |
| | Communications Method | | Half-duplex | | | |
| | Synchronization Method | | Start-stop | | | |
| | Baud Rate | | 0.3, 0.6, 1.2, 2.4, 4.8, 9.6, 19.2, 38.4, 57.6, or 115.2 (kbps) | | | |
| | Transmission Distance | | 15 m max. | | | |
| | EtherNet/IP Port | | - | | | |
| | Transmission Specifications | Media Access Method | CSMA/CD | | | |
| | | Modulation | Baseband | | | |
| | | Transmission Paths | Star | | | |
| | | Baud Rate | 100 Mbps (100Base-TX) | | | |
| | | Transmission Media | Shielded twisted-pair (STP) cable; Categories: 5, 5e | | | |
| | | Transmission Distance | 100 m (between hub and node) | | | |
| | | Number of Cascade Connections | No restrictions if switching hub is used. | | | |
| | Communications Specifications | CIP Communications: Tag Data Links | | - | | |
| | | Number of Connections | | 256 | | |
| | | Packet Interval (Refresh period) | | 0.5 to 10,000 ms (Unit: 0.5 ms) Can be set for each connection. (Data will be refreshed at the set interval, regardless of the number of nodes.) | | |
| | | Permissible Communications Band | | 6,000 pps *1 | | |
| | | Number of Registerable Tag | | 256 | | |
| | | Type of Tags | | CIO, DM, EM, HR, WR, and Network symbols | | |
| | | Number of Tags per Connection | | 8 (Seven tags if PLC status is included in the segment.) | | |
| | | Maximum Link Data Size per Node | | 184,832 words | | |
| | | Maximum Data Size per Connection | | 252 or 722 words *2 (Data is synchronized within each connection.) | | |
| | | Number of Registrable Tag Set | | 256 (1 connection = 1 segment) | | |
| | | Maximum Tag Set Size | | 722 words (One word is used when PLC status is included in the segment.) | | |
| | | Maximum Number of Tags Refreshable in a Single Cycle of CPU Unit *3 | | Output/send (CPU Unit to EtherNet/IP): 256 Input/receive (EtherNet/IP to CPU Unit): 256 | | |
| | | Data Size Refreshable in a Single Cycle of CPU Unit *3 | | Output/send (CPU to EtherNet/IP): 6,432 words Input/receive (EtherNet/IP to CPU): 6,432 words | | |
| Change of Tag Data Link Parameter Settings during Operation | | OK *4 | | | | |
| Multi-cast Packet Filter *5 | | OK | | | | |
| CIP Communications: Explicit Messages | | - | | | | |
| Class 3 (Connection Type) | | Number of connections: 128 | | | | |
| UCMM (Non-connection Type) | | Maximum number of clients that can communicate at the same time: 32 Maximum number of servers that can communicate at the same time: 32 | | | | |
| CIP Routing | | OK (CIP routing is enabled for the following remote Units: CJ1W-EIP21, CJ2H-CPU6□-EIP, CJ2M-CPU3□, and CS1W-EIP21.) | | | | |
| FINS Communications | | - | | | | |
| FINS/UDP | | OK | | | | |
| FINS/TCP | | 16 connections max. | | | | |
| EtherNet/IP Conformance Test | | Conforms to A5. | | | | |
| EtherNet/IP Interface | | 10Base-T/100Base-TX Auto Negotiation/Fixed Setting | | | | |

- *1. "Packets per second" is the number of communications packets that can be processed per second.
- *2. Large Forward Open (CIP optional specification) must be supported in order for 505 to 1,444 bytes to be used as the data size. Application is supported between CS/CJ-series PLCs. When connecting to devices from other manufacturers, make sure that the devices support the Large Forward Open specification.
- *3. If the maximum number is exceeded, refreshing will require more than one CPU Unit cycle.
- *4. When changing parameters, however, the EtherNet/IP port where the change is made will be restarted. In addition, a timeout will temporarily occur at the other node that was communicating with that port, and it will then recover automatically.
- *5. The EtherNet/IP port supports an IGMP client, so unnecessary multicast packets are filtered by using a switching hub that supports IGMP snooping.

Function Specifications

| Functions | | | Description | |
|-------------------------------|--|--|--|---|
| Cycle Time Management | Minimum Cycle Time | | A minimum cycle time can be set. (0.2 to 32,000 ms; Unit: 0.1 ms) The minimum cycle time setting can be changed in MONITOR mode. (Unit version 1.1 or higher) | |
| | Cycle Time Monitoring | | The cycle time is monitored. (0.01 to 40,000 ms; Unit: 0.01 ms) | |
| | Background Processing | | Instructions with long execution times can be executed over multiple cycles to prevent fluctuations in the cycle time. | |
| Unit (I/O) Management | Basic I/O Units, Special I/O Units, and CPU Bus Units | I/O Refreshing | Cyclic Refreshing | Cyclic refreshing of Basic I/O Units, Special I/O Units, and CPU Bus Units |
| | | | Immediate Refreshing | I/O refreshing by immediate refreshing instructions |
| | | | Refreshing by IORF | I/O refreshing by IORF instruction |
| | | Unit Recognition at Startup | The number of units recognized when the power is turned ON is displayed. | |
| | Basic I/O Units | Input Response Time Setting | | The input response times can be set for Basic I/O Units. The response time can be increased to reduce the effects of chattering and noise at input contacts. The response time can be decreased to enable detecting shorter input pulses. |
| | | Load OFF Function | | All of the outputs on Basic I/O Units can be turned OFF when an error occurs in RUN or MONITOR mode. |
| | | Basic I/O Unit Status Monitoring | | Alarm information can be read from Basic I/O Units and the number of Units recognized can be read. |
| | Special I/O Units and CPU Bus Units | Unit Restart Bits to Restart Units | | A Special I/O Unit or CPU Bus Unit can be restarted. |
| | | Synchronous Unit Operation | | The start of processing for all the specified Units can be synchronized at a fixed interval. Maximum number of Units: 10 Units (Only Units that support Synchronous Operation Mode can be used.) Synchronous operation cycle: 0.5 to 10 ms (default: 2 ms) Maximum number of words for synchronous data refreshing: 96 words (total of all Units) |
| | Configuration Management | Automatic I/O Allocation at Startup | | I/O words can be automatically allocated to the Basic I/O Units that are connected in the PLC to start operation automatically without registering Units into I/O tables. |
| I/O Table Creation | | The current unit configuration can be registered in I/O tables to prevent it from being changed, to reserve words, and to set words. | | |
| Rack/Slot First Word Settings | | The first words allocated to a Units on the Racks can be set. | | |
| Memory Management | Holding I/O Memory when Changing Operating Modes | | The status of I/O memory can be held when the operating mode is changed or power is turned ON. The forced-set/reset status can be held when the operating mode is changed or power is turned ON. | |
| | File Memory | | Files (such as program files, data files, and symbol table files) can be stored in Memory Card, EM File Memory, or Comment Memory. | |
| | Built-in Flash Memory | | The user program and Parameter Area can be backed up to an internal flash memory when they are transferred to the CPU Unit. | |
| | EM File Function | | Parts of the EM Area can be treated as file memory. | |
| | Storing Comments | | I/O comments can be stored as symbol table files in a Memory Card, EM file memory, or comment memory. | |
| | EM Configuration | | EM Area can be set as trace memory or EM file memory. | |
| Memory Cards | Automatic File Transfer at Startup | | A program file and parameter files can be read from a Memory Card when the power is turned ON. | |
| | Program Replacement during PLC Operation | | The whole user program can be read from a Memory Card to CPU Unit during operation. | |
| | Function for Reading and Writing Data from a Memory Card | | Data in I/O memory in the CPU Unit can be written to a Memory Card in CSV/TXT format. Data in CSV/TXT format in the Memory Card can be read to I/O memory in the CPU Unit. | |

| Function | | Description |
|--|--|--|
| Communications | | – |
| Communications | Peripheral (USB) Port | Peripheral Bus |
| | Bus for communications with various kinds of Support Software running on a personal computer. High-speed communications are supported. | |
| | Serial Port | |
| | – | |
| | Host Link (SYSWAY) Communications | |
| | Host Link commands or FINS commands placed between Host Link headers and terminators can be sent from a host computer or PT to read/write I/O memory, read/control the operating mode, and perform other operations for PLC. | |
| | No-protocol Communications | |
| | I/O instructions for communications ports (such as TXD/RXD instructions) can be used for data transfer with peripheral devices such as bar code readers and printers. | |
| | NT Link Communications | |
| | I/O memory in the PLC can be allocated and directly linked to various PT functions, including status control areas, status notification areas, touch switches, lamps, memory tables, and other objects. | |
| Peripheral Bus | | Bus for communications with various kinds of Support Software running on a personal computer. High-speed communications are supported. |
| Serial Gateway | | This gateway enables receiving and automatically converting FINS to the CompoWay/F. |
| EtherNet/IP Port | | 100Base-TX/10Base-T Protocols: TCP/IP, UDP, ARP, ICMP (ping only), BOOTP Applications: FINS, CIP, SNTP, DNS (Client), FTP (Server) |
| CIP Communications Service | Tag Data Links | Programless cyclic data exchanges with the devices on the EtherNet/IP network. |
| | Message Communications | Any CIP commands can be received from the devices on the EtherNet/IP network. |
| FINS Communications Service | Message Communications | Any FINS commands can be transferred with the devices on the EtherNet/IP network. |
| | | |
| Interrupt | Scheduled Interrupts | |
| | Tasks can be executed at a specified interval (minimum of 0.2 ms or 0.1 ms *, Unit: 0.1 ms). * When High-speed interrupt function is used. | |
| | Power OFF Interrupts | |
| | A task can be executed when CPU Unit's power turns OFF. | |
| | I/O Interrupt Tasks | |
| A task can be executed when an input signal is input to an Interrupt Input Unit. | | |
| External Interrupt Tasks | | |
| A task can be executed when interrupts are requested from a Special I/O Unit or a CPU Bus Unit. | | |
| High-speed Interrupt Function | | |
| Improves performance for executing interrupt tasks with certain restrictions. (Unit version 1.1 or later.) | | |
| Clock | Clock Function | |
| | Clock data is stored in memory. Accuracy (Accuracy depends on the temperature.) Ambient temperature of 55°C: –3.5 to +0.5 min error per month Ambient temperature of 25°C: –1.5 to +1.5 min error per month Ambient temperature of 0°C: –3 to +1 min error per month | |
| | Operation Start Time Storage | |
| | The time when operating mode was last changed to RUN mode or MONITOR mode is stored. | |
| | Operation Stop Time Storage | |
| | The last time a fatal error occurred or the last time the operating mode was changed to PROGRAM mode is stored. | |
| | Startup Time Storage | |
| | The time when the power was turned ON is stored. | |
| Power Interruption Time Storage | | |
| The time when the power is turned OFF is stored. | | |
| Total Power ON Time Calculation | | |
| The total time that the PLC has been ON is stored in increments of 10 hours. | | |
| Power ON Clock Data Storage | | |
| A history of the times when the power was turned ON is stored. | | |
| User Program Overwritten Time Storage | | |
| The time that the user program was last overwritten is stored. | | |
| Parameter Date Storage | | |
| The time when the Parameter Area was overwritten is stored. | | |
| Power Supply Management | Memory Protection | |
| | Holding Area data, DM Area data, EM Area data, Counter Completion Flags, and counter present values are held even when power is turned OFF. CIO Area, Work Area, some Auxiliary Area data, and Timer Completion Flags, timer present values, index registers, and data registers can be protected by turning ON the IOM Hold Bit in the Auxiliary Area, and by also setting the IOM Hold Bit to "Hold" in the PLC Setup. | |
| | Power OFF Detection Time Setting | |
| | The detection time for power interruptions can be set. AC power supply: 10 to 25 ms (variable) DC power supply: 2 to 5 ms (CJ1W-PD022) or 2 to 20 ms (CJ1W-PD025) | |
| Power OFF Detection Delay Time | | |
| The detection of power interruptions can be delayed: 0 to 10 ms (Not supported by the CJ1W-PD022.) | | |
| Number of Power Interruptions Counter | | |
| The number of times power has been interrupted is counted. | | |
| Function Blocks | | Standard programming can be encapsulated as function blocks. |
| Languages in Function Block Definitions | | Ladder programming or structured text |
| Debugging | Online Editing | |
| | The program can be changed during operation (in MONITOR or PROGRAM mode), except for block programming areas. | |
| | Force-Set/Reset | |
| | Specified bits can be set or reset. Force-set/reset to the EM Area is enabled by specifying a start bank in parameter setting. (unit version 1.2 or higher) | |
| | Differentiate Monitoring | |
| ON/OFF changes in specified bits can be monitored. | | |
| Data Tracing | | |
| The specified I/O memory data can be stored in the trace memory in the CPU Unit. The triggers can be set. • The trace data can be uploaded during data tracing using CX-Programmer, which enables continuously logging the data by constantly uploading the trace data (trace data uploading during tracing). • Data tracing can be automatically started when operation is started (i.e., when the operating mode is changed from PROGRAM mode to MONITOR or RUN mode). | | |
| Storing Location of Error when an Error Occurs | | |
| The location and task number where execution stopped for a program error is recorded. | | |
| Program Check | | |
| The programs can be checked for items such as no END instruction and FALS/FAL errors at startup. | | |

| Function | | Description | |
|---|---|--|---|
| Self-diagnosis and Restoration | Error Log | A function is provided to store predefined error codes in CPU Unit, error information, and time at which the error occurred. | |
| | CPU Error Detection | CPU Unit WDT errors are detected. | |
| | User-defined Failure Diagnosis | Errors can be generated for user-specified conditions: Non-fatal errors (FAL) and fatal errors (FALS). Program section time diagnosis and program section logic diagnosis are supported (FPD instruction). | |
| | Load OFF Function | This function turns OFF all outputs from Output Units when an error occurs. | |
| | RUN Output | The RUN output from the CJ1W-PA205R turns ON while CPU Unit is in RUN mode or MONITOR mode. | |
| | Basic I/O Load Short-circuit Detection | This function provides alarm information from Basic I/O Units that have load short-circuit protection. | |
| | Failure Point Detection | The time and logic of an instruction block can be analyzed using the FPD instruction. | |
| | CPU Standby Detection | This function indicates when the CPU Unit is on standby because all Special I/O Units and CPU Bus Units have not been recognized at the startup in RUN or MONITOR mode. | |
| | Non-fatal Error Detection | System FAL Error Detection (User-defined non-fatal error) | This function generates a non-fatal (FAL) error when the user-defined conditions are met in program. |
| | | Duplicate Refreshing Error Detection | This function detects an error when an immediate refreshing Instruction in an interrupt task is competing with I/O refreshing of a cyclic task. |
| | | Basic I/O Unit Error Detection | This function detects the errors in Basic I/O Units. |
| | | Backup Memory Error Detection | This function detects errors in the memory backup of the user programs and parameter area (backup memory). |
| | | PLC Setup Error Detection | This function detects setting errors in the PLC Setup. |
| | | CPU Bus Unit Error Detection | This function detects an error when there is an error in data exchange between the CPU Unit and a CPU Bus Unit. |
| | | Special I/O Unit Error Detection | This function detects an error when there is an error in data exchange between the CPU Unit and a Special I/O Unit. |
| | | Tag Memory Error Detection | This function detects errors in tag memory. |
| | | Battery Error Detection | This function detects an error when a battery is not connected to the CPU Unit or when the battery voltage drops. |
| | | CPU Bus Unit Setting Error Detection | This function detects an error when the model of a CPU Bus Unit in the registered I/O tables does not agree with the model that is actually mounted in the PLC. |
| | | Special I/O Unit Setting Error Detection | This function detects an error when the model of a Special I/O Unit in the registered I/O tables does not agree with the model of Unit that is actually mounted. |
| | Fatal Error Detection | Memory Error Detection | This function detects errors that occur in memory of the CPU Unit. |
| | | I/O Bus Error Detection | This function detects when an error occurs in data transfers between the Units mounted in Rack slots and the CPU Unit and detects when the End Cover is not connected to the CPU Rack or an Expansion Rack. |
| | | Unit/Rack Number Duplication Error | This function detects an error when the same unit number is set for two or more Units, the same word is allocated to two or more Basic I/O Units, or the same rack number is set for two or more Racks. |
| | | Too Many I/O Points Error Detection | This function detects an error when the total number of I/O points set in the I/O tables or the number of Units per Rack exceeds the specified range. |
| | | I/O Setting Error Detection | This function detects an error when the number of Units in the registered I/O tables does not agree with the actual number of Units that is mounted, or an Interrupt Unit has been connected in the wrong position, i.e., not in slot 0 to 3. |
| | | Program Error Detection | This function detects errors in programs. |
| | | Instruction Processing Error Detection | This function detects an error when the given data value is invalid when executing an instruction, or execution of instruction between tasks was attempted. |
| | | Indirect DM/EM BCD Error Detection | This function detects an error when an indirect DM/EM address in BCD mode is not BCD. |
| Illegal Area Access Error Detection | | This function detects an error when an attempt is made to access an illegal area with an instruction operand. | |
| No END Error Detection | | This function detects an error when there is no END instruction at the end of the program. | |
| Task Error Detection | | This function detects an error when there are no tasks that can be executed in a cycle, there is no program for a task, or the execution condition for an interrupt task was met but there is no interrupt task with the specified number. | |
| Differentiation Overflow Error Detection | | This function detects an error when too many differentiated instructions are entered or deleted during online editing (131,072 times or more). | |
| Invalid Instruction Error Detection | | This function detects an error when an attempt is made to execute an instruction that is not defined in the system. | |
| User Program Area Overflow Error Detection | | This function detects an error when instruction data is stored after the last address in user program area. | |
| Cycle Time Exceeded Error Detection | This function monitors the cycle time (10 to 40,000 ms) and stops the operation when the set value is exceeded. | | |
| Fatal Error Detection (Continued from previous page) | System FALS Error Detection (User-defined Fatal Error) | This function generates a fatal (FALS) error when the user-defined conditions are met in program. | |
| | Version Error Detection | This function detects an error when a user program includes a function that is not supported by the current unit version. | |
| | Memory Card Transfer Error Detection | This function detects an error when the automatic file transfer from Memory Card fails at startup. | |
| Memory Self-restoration Function | | This function performs a parity check on the user program area and self-restoration data. | |

| Function | | Description |
|-------------|---|--|
| Maintenance | Simple Backup Function | This function collectively backs up the data in CPU Unit (user programs, parameters, and I/O memory) and internal backup data in the I/O Units. |
| | Unsolicited Communications | A function that allows the PLC to use Network Communications Instruction to send required FINS commands to a computer connected via a Host Link |
| | Remote Programming and Monitoring | Host Link communications can be used for remote programming and remote monitoring through a Controller Link, Ethernet, DeviceNet, or SYSMAC LINK Network. Communications across network layers can be performed. Controller Link or Ethernet: 8 layers DeviceNet or SYSMAC LINK: 3 layers |
| | Automatic Online Connection via Network | Direct Serial Connection This function enables automatically connecting to the PLC online when the CX-Programmer is directly connected by a serial connection (peripheral (USB) port or serial port). Via Networks This function enables connecting the CX-Programmer online to a PLC that is connected via an EtherNet/IP network. |
| Security | Read Protection using Password | This function protects reading and displaying programs and tasks using passwords. Write protection: Set using the DIP switch. Read protection: Set a password using the CX-Programmer. |
| | FINS Write Protection | This function prohibits writing by using FINS commands sent over the network. |
| | Unit Name Function | This function allows the users to give any names to the Units. Names are verified at online connection to prevent wrong connection |
| | Hardware ID Using Lot Numbers | This function sets operation protection by identifying hardware using the user programs according to lot numbers stored in the Auxiliary Area. |

Unit Versions

| Units | Models | Unit version |
|----------------|----------------|--|
| CJ2H CPU Units | CJ2H-CPU6□-EIP | CPU: Unit version 1.4 EIP: Unit version 2.0 |
| | | CPU: Unit version 1.3 EIP: Unit version 2.0 |
| | | CPU: Unit version 1.2 EIP: Unit version 2.0 |
| | | CPU: Unit version 1.1 EIP: Unit version 2.0 |
| | | CPU: Unit version 1.0 EIP: Unit version 2.0 |

Function Support by Unit Version

Unit Version 1.4 or Later

CX-Programmer version 9.3 or higher must be used to enable using the functions added for unit version 1.4.

| Unit Model | Unit version | CJ2H CPU Unit CJ2H-CPU6□-EIP | |
|---|--------------|---------------------------------|-----------------------------|
| | | Unit version 1.4 or higher | Unit version 1.3 or earlier |
| Item | | | |
| Synchronous unit operation function Position Control Units with EtherCAT interface CJ1W-NC□82 work for synchronous unit operation. | | Supported. | Not supported. |

Unit Version 1.3 or Later

CX-Programmer version 9.1 or higher must be used to enable using the functions added for unit version 1.3.

| Unit Model | Unit version | CJ2H CPU Unit CJ2H-CPU6□-EIP | |
|--|--|---------------------------------|-----------------------------|
| | | Unit version 1.3 or later | Unit version 1.2 or earlier |
| Item | | | |
| Special instructions for certain Special I/O Units | CJ1W-NC281/NC481/NC881 Position Control Units: PCU HIGH-SPEED POSITIONING (NCDMV(218)) | Supported. | Not supported. |
| | CJ1W-NC281/NC481/NC881 Position Control Units: PCU POSITIONING TRIGGER (NCDTR(219)) | Supported. | Not supported. |
| New special instructions | SIGNED AREA RANGE COMPARE: ZCPS(088) | Supported. | Not supported. |
| | DOUBLE SIGNED AREA RANGE COMPARE: ZCPSL(116) | Supported. | Not supported. |

Unit Version 1.2 or Later

CX-Programmer version 8.3 or higher must be used to enable using the functions added for unit version 1.2.

| Unit Model | Unit version | CJ2H CPU Unit CJ2H-CPU6□-EIP | |
|-----------------------------|--------------|---------------------------------|-----------------------------|
| | | Unit version 1.2 or higher | Unit version 1.1 or earlier |
| Item | | | |
| EM force-set/reset function | | Supported. | Not supported. |

Note: User programs that use functions of CJ2H CPU Units with unit version 1.2 or later cannot be used with CJ2H CPU Units with unit version 1.1 or earlier. If an attempt is made to transfer a program that uses any of these functions from the CX-Programmer to a CPU Unit with unit version 1.1 or earlier, an error will be displayed and it will not be possible to download to the CPU Unit.

Unit Version 1.1 or Later

CX-Programmer version 8.1 or higher must be used to enable using the functions added for unit version 1.1.

| Item | Unit | CJ2H CPU Unit | |
|---|--------------|----------------------------|------------------|
| | Model | CJ2H-CPU6□-EIP | |
| | Unit version | Unit version 1.1 or higher | Unit version 1.0 |
| High-speed interrupt function Decreased overhead time for interrupt tasks Minimum interval setting of 0.1 ms for Scheduled Interrupt Task | | Supported. | Not supported. |
| Changing the minimum cycle time setting in MONITOR mode | | Supported. | Not supported. |
| Synchronous unit operation function Position Control Units (High-speed type) CJ1W-NC□□4 work for synchronous unit operation. | | Supported. | Not supported. |
| Addition of Immediate refreshing instruction only for specific Special I/O Units and CPU Bus Units For CJ1W-AD042 : Analog Input Direct Convert AIDC (216) For CJ1W-DA042V : Analog Output Direct Convert AODC (217) For CJ1W-SCU22/32/42 : Direct Receive Via Serial Communications Unit DRXDU (261) Direct Transmit Via Serial Communications Unit DTXDU (262) | | Supported. | Not supported. |

Note: User programs that use functions of CJ2H CPU Units with unit version 1.1 or later cannot be used with CJ2H CPU Units with unit version 1.0. If an attempt is made to transfer a program that uses any of these functions from the CX-Programmer to a CPU Unit with unit version 1.0, an error will be displayed and it will not be possible to download to the CPU Unit. If a program file (extension: .OBJ) that uses any of these functions is transferred to a CPU Unit with unit version 1.0, a program error will occur when operation starts or when the function starts and operation of the CPU Unit will stop.

Unit Versions and Programming Devices

The following tables show the relationship between unit versions and CX-Programmer versions.

Unit Versions and Programming Devices

| CPU Unit | Functions | | Required Programming Device | | | | | | Programming Console |
|------------------------------------|--------------------------------------|-------------------------|-----------------------------|----------|--------------------|----------|--------------------|--------------------|---------------------|
| | | | CX-Programmer | | | | | | |
| | | | Ver. 7.1 or lower | Ver. 8.0 | Ver. 8.1/ Ver. 8.2 | Ver. 8.3 | Ver. 9.1/ Ver. 9.2 | Ver. 9.3 or higher | |
| CJ2H-CPU6□-EIP Unit version 1.4 | Functions added for unit version 1.4 | Using new functions | - | - | - | - | - | OK | - *3 |
| | | Not using new functions | - | OK *1 | OK *1 | OK | OK | OK | |
| CJ2H-CPU6□-EIP Unit version 1.3 | Functions added for unit version 1.3 | Using new functions | - | - | - | - | OK | OK | |
| | | Not using new functions | - | OK *1 | OK *1 | OK | OK | OK | |
| CJ2H-CPU6□-EIP Unit version 1.2 | Functions added for unit version 1.2 | Using new functions | - | - | - | OK | OK | OK | |
| | | Not using new functions | - | OK *1 | OK *1 | OK | OK | OK | |
| CJ2H-CPU6□-EIP Unit version 1.1 | Functions added for unit version 1.1 | Using new functions | - | - | OK *2 | OK | OK | OK | |
| | | Not using new functions | - | OK *1 | OK | OK | OK | OK | |
| CJ2H-CPU6□-EIP Unit version 1.0 | Functions for unit version 1.0 | | - | OK | OK | OK | OK | OK | |

*1. It is not necessary to upgrade the version of the CX-Programmer if functionality that was enhanced for the upgrade of the CPU Unit will not be used.

*2. CX-Programmer version 8.2 or higher is required to use the added functions in CJ2H CPU Units (CJ2H-CPU6□-EIP) with unit version 1.1. However only High-speed interrupt function and Changing the minimum cycle time setting in MONITOR mode are supported in CX-Programmer version 8.02.

*3. A Programming Console cannot be used with a CJ2H CPU Unit.

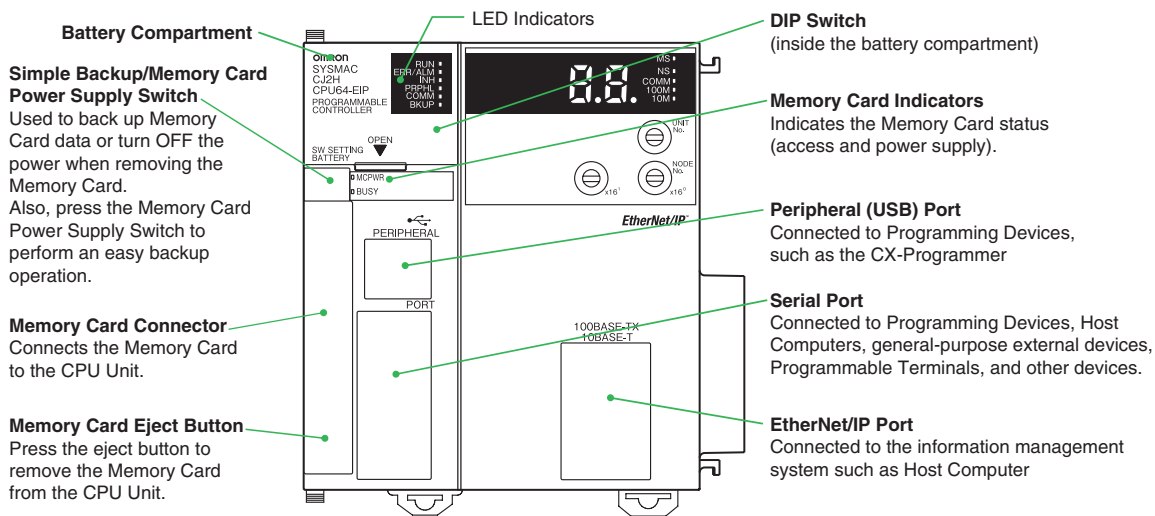
Device Type Setting

The unit version does not affect the setting made for the device type on the CX-Programmer. Select the device type as shown in the following table regardless of the unit version of the CPU Unit.

| Series | CPU Unit group | CPU Unit model | Device type setting on CX-Programmer Ver. 8.0 or higher |
|-----------|----------------|----------------|---|
| CJ Series | CJ2H CPU Units | CJ2H-CPU6□-EIP | CJ2H |

External Interface

A CJ2H CPU Unit (CJ2H-CPU6□-EIP) provides three communications ports for external interfaces: a peripheral (USB) port, a serial port and an EtherNet/IP port.



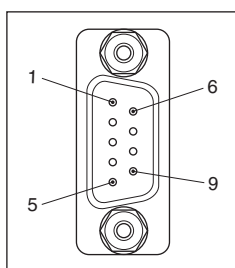
Peripheral (USB) Port

| Item | Specification |
|-----------------------|------------------------------------|
| Baud Rate | 12 Mbps max. |
| Transmission Distance | 5 m max. |
| Interface | USB 2.0-compliant B-type connector |
| Protocol | Peripheral Bus |

Serial Port

| Item | Specification |
|-----------------------|---|
| Communications method | Half duplex |
| Synchronization | Start-stop |
| Baud rate | 0.3/0.6/1.2/2.4/4.8/9.6/19.2/38.4/57.6/115.2 kbps * |
| Transmission distance | 15 m max. |
| Interface | EIA RS-232C |
| Protocol | Host Link, NT Link, 1:N, No-protocol, or Peripheral Bus |

* Baud rates for the RS-232C are specified only up to 19.2 kbps. The CJ Series supports serial communications from 38.4 kbps to 115.2 kbps, but some computers cannot support these speeds. Lower the baud rate if necessary.



| Pin No. | Signal | Name | Direction |
|----------------|----------|---------------------|-----------|
| 1 | FG | Protection earth | - |
| 2 | SD (TXD) | Send data | Output |
| 3 | RD (RXD) | Receive data | Input |
| 4 | RS (RTS) | Request to send | Output |
| 5 | CS (CTS) | Clear to send | Input |
| 6 | 5 V | Power supply | - |
| 7 | DR (DSR) | Data set ready | Input |
| 8 | ER (DTR) | Data terminal ready | Output |
| 9 | SG (0 V) | Signal ground | - |
| Connector hood | FG | Protection earth | - |

Note: Do not use the 5-V power from pin 6 of the RS-232C port for anything but CJ1W-CIF11 RS-422A Conversion Adapter, NT-AL001 RS-232C/RS-422A Conversion Adapter and NV3W-M□20L Programmable Terminal. The external device or the CPU Unit may be damaged.

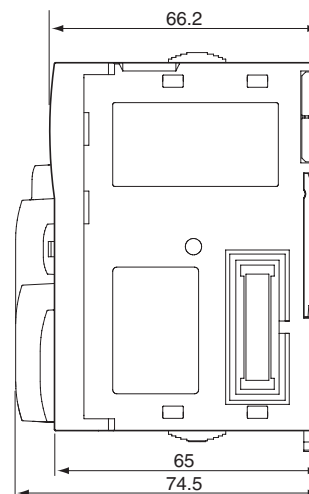
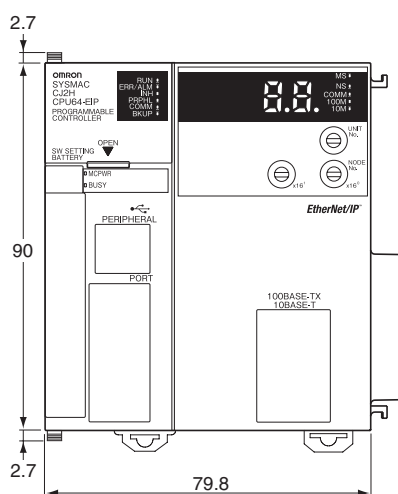
EtherNet/IP Port

| Item | Specification |
|-------------------------------|--|
| Media Access Method | CSMA/CD |
| Modulation | Baseband |
| Transmission Paths | Star |
| Baud Rate | 100 Mbps (100Base-TX) |
| Transmission Media | Shielded twisted-pair (STP) cable; Categories: 5, 5e |
| Transmission Distance | 100 m (between hub and node) |
| Number of Cascade Connections | No restrictions if switching hub is used. |
| Communications | CIP Communications (tag data links, Explicit Messages). FINS communications |

Dimensions

(Unit: mm)

CJ2H CPU Unit
CJ2H-CPU6□-EIP



Related Manuals

| Cat. No. | Model | Manual | Application | Description |
|----------|--|--|--|---|
| W472 | CJ2H-CPU6□-EIP CJ2H-CPU6□ CJ2M-CPU□□ | CJ-series CJ2 CPU Unit Hardware User's Manual | Hardware specifications for CJ2 CPU Units | Describes the following for CJ2 CPU Units: <ul style="list-style-type: none"> • Overview and features • Basic system configuration • Part nomenclature and functions • Mounting and setting procedure • Remedies for errors • Also refer to the <i>Software User's Manual</i> (W473). |
| W473 | CJ2H-CPU6□-EIP CJ2H-CPU6□ CJ2M-CPU□□ | CJ-series CJ2 CPU Unit Software User's Manual | Software specifications for CJ2 CPU Units | Describes the following for CJ2 CPU Units: <ul style="list-style-type: none"> • CPU Unit operation • Internal memory • Programming • Settings • Functions built into the CPU Unit Also refer to the <i>Hardware User's Manual</i> (W472) |
| W474 | CJ2H-CPU6□-EIP CJ2H-CPU6□ CJ2M-CPU3□ CJ2M-CPU1□ CS1G/H-CPU□□H CS1G/H-CPU□□-V1 CJ1G/H-CPU□□H CJ1G-CPU□□ CJ1M-CPU□□ NSJ□-□□□□(□)-□□□□ | CS/CJ/NSJ-series Instructions Reference Manual | Information on instructions | Describes each programming instruction in detail. Also refer to the <i>Software User's Manual</i> (W473) when you do programming. |
| W342 | CJ2H-CPU6□-EIP CJ2H-CPU6□ CJ2M-CPU□□ CS1G/H-CPU□□H CS1G/H-CPU□□-V1 CS1D-CPU□□H CS1D-CPU□□S CS1W-SCU□□-V1 CS1W-SCB□□-V1 CJ1H-CPU□□H-R CJ1G/H-CPU□□H CJ1G-CPU□□P CJ1M-CPU□□ CJ1G-CPU□□ CJ1W-SCU□□-V1 CP1H-X□□□□-□ CP1H-XA□□□□-□ CP1H-Y□□□□-□ NSJ□-□□□□(□)-□□□□ | CS/CJ/CP/NSJ-series Communications Command Reference Manual | Information on communications for CS/CJ/CP-series CPU Units and NSJ-series Controllers | Describes C-mode commands and FINS commands Refer to this manual for a detailed description of commands for communications with the CPU Unit using C mode commands or FINS commands. Note: This manual describes the communications commands that are addressed to CPU Units. The communications path that is used is not relevant and can include any of the following: serial ports on CPU Units, communications ports on Serial Communications Units/Boards, and Communications Units. For communications commands addressed to Special I/O Units or CPU Bus Units, refer to the operation manual for the related Unit. |
| W463 | CXONE-AL□□C-V□/ AL□□D-V□ | CX-One Setup Manual | Installing software from the CX- One | Provides an overview of the CX-One FA Integrated Tool Package and describes the installation procedure. |
| W446 | WS02-CXPC□-V□ | CX-Programmer Operation Manual | Support Software for Windows computers CX-Programmer operating procedure | Describes operating procedures for the CX-Programmer. Also refer to the <i>Software User's Manual</i> (W473) and <i>Instructions Reference Manual</i> (W474) when you do programming. |
| W447 | | CX-Programmer Operation Manual Functions Blocks/ Structured Text | | |
| W469 | | CX-Programmer Operation Manual SFC Programming | | |
| W366 | WS02-SIMC1-E | CS/CJ/CP/NSJ-series CX-Simulator Operation Manual | Operating procedures for CX- Simulator Simulation Support Software for Windows computers Using simulation in the CX- Programmer with CX- Programmer version 6.1 or higher | Describes the operating procedures for the CX-Simulator. When you do simulation, also refer to the <i>CX-Programmer Operation Manual</i> (W446), <i>Software User's Manual</i> (W473), and <i>CS/CJ/NSJ series Instructions Reference Manual</i> (W474). |
| W464 | CXONE-AL□□C-V□/ CXONE-AL□□D-V□ | CS/CJ/CP/NSJ-series CX-Integrator Network Configuration Software Operation Manual | Network setup and monitoring | Describes the operating procedures for the CX-Integrator. |

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